

Qubit triple measurement uncertainty

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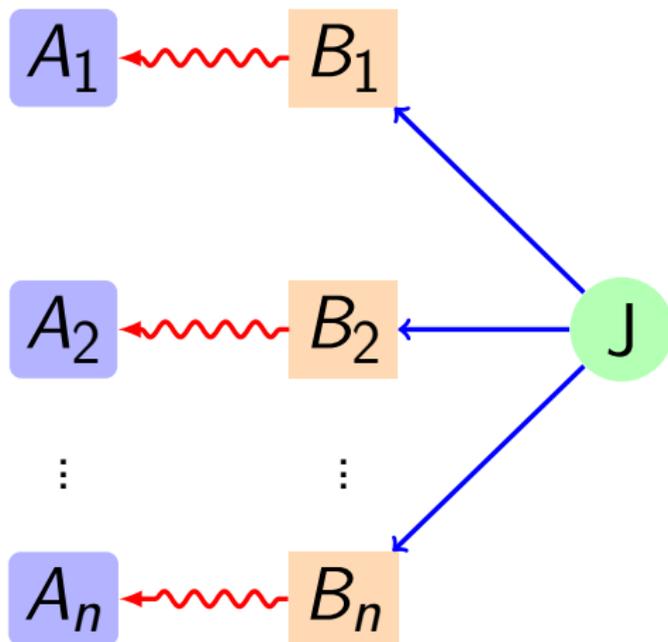
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- 1 Measurement uncertainty basics
- 2 Covariance
- 3 Specific case

The problem

- Fix a Hilbert space \mathcal{H}
- Have some family $\{A_i \mid i \in 1\dots n\}$ of *incompatible* observables we would like to measure $A_i : \Omega_i \rightarrow \mathcal{L}(\mathcal{H})$
- Consider an arbitrary family of compatible observables, with the same outcome spaces $B_i : \Omega_i \rightarrow \mathcal{L}(\mathcal{H})$
- Ensure compatibility by requiring that the B_i are marginals of some joint $J : \prod_i \Omega_i \rightarrow \mathcal{L}(\mathcal{H})$
- Choose a figure of merit δ for an approximation and explore the set of allowed vectors $(\delta(A_1, B_1), \dots, \delta(A_n, B_n))$

The problem



- POVM + state = probability distribution
- Statisticians know many ways of measuring similarity of probability distributions
- Here we take the worst case difference of the probabilities
- Symbolically

$$d(P, Q) = \sup_{\omega \in \Omega} |P(\omega) - Q(\omega)| \quad (1)$$

- Which state to use? -The worst one!
- Sup “norm” of a POVM

$$\|E\|_{\text{sup}} := \sup_{\rho} \sup_{\omega \in \Omega} |\text{tr}(E(\omega)\rho)| \quad (2)$$

$$d(E, F) = \|E - F\|_{\text{sup}} \quad (3)$$

- Exploring the space of joints is hard
- $J : \prod_i \Omega_i \rightarrow \mathcal{L}(\mathcal{H})$ is often a POVM with very many outcomes
- Explicit parameterisations are not known
- Sometimes we can impose *covariance* to reduce the search space
 - Dammeier, Schwonnek and Werner NJP 1709.3046
 - Carmeli, Heinosaari, Reitzner, Schultz and Toigo Mathematics 2016 4 54
 - Busch, Kiukas and Werner arXiv:1604.00566
 - many others

Covariance (1)

- Given a group G , with an action (\cdot) on a set Ω , and an (anti-)unitary projective representation $\{U_g \mid g \in G\}$ acting on Hilbert space \mathcal{H} we say an observable $E : \Omega \rightarrow \mathcal{L}(\mathcal{H})$ is *covariant* if

$$E(g \cdot \omega) = U_g E(\omega) U_g^*, \quad \forall g \in G, \omega \in \Omega \quad (4)$$

- We can't require this in general, but covariance is often present in physically relevant scenarios
- For all self-adjoint operators ρ , and for all $g, h \in G$ we have

$$U_g U_h \rho U_h^* U_g^* = U_{gh} \rho U_{gh}^* \quad (5)$$

Covariance (2)

- Given G and U_g we can define the *group averaging map*, which maps POVMs to POVMs

$$M(E)(\omega) = \frac{1}{|G|} \sum_{g \in G} U_{g^{-1}} E(g.\omega) U_{g^{-1}}^* \quad (6)$$

- Covariant observables are invariant under M
- It is easy to verify that $M(E)$ is always covariant
- Under an additional (natural) assumption M also acts to reduce the sup-norm of a POVM: $\forall \omega, \omega' \in \Omega$

$$|\{g \in G \mid g.\omega = \omega'\}| = \frac{|G|}{|\Omega|} \quad (7)$$

Qubit orthogonal triple

- Attempting to simultaneously approximate the observables

$$A_{\pm} = \frac{1}{2} (1 \pm \vec{a} \cdot \vec{\sigma}) \quad (8)$$

$$B_{\pm} = \frac{1}{2} (1 \pm \vec{b} \cdot \vec{\sigma}) \quad (9)$$

$$C_{\pm} = \frac{1}{2} (1 \pm \vec{c} \cdot \vec{\sigma}), \quad (10)$$

where \vec{a} , \vec{b} , \vec{c} are pairwise orthogonal

- Column vectors will be written in the \vec{a} , \vec{b} , \vec{c} basis so

$$\vec{a} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \quad \vec{b} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \quad \vec{c} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \quad (11)$$

- Define

$$D_k = \frac{1}{2} \left(1 + kd_0 + k\vec{d} \cdot \vec{\sigma} \right) = \sum_{l,m} J_{klm} \quad (12)$$

$$E_l = \frac{1}{2} \left(1 + ld_0 + l\vec{d} \cdot \vec{\sigma} \right) = \sum_{k,m} J_{klm} \quad (13)$$

$$F_m = \frac{1}{2} \left(1 + md_0 + m\vec{d} \cdot \vec{\sigma} \right) = \sum_{k,l} J_{klm}, \quad (14)$$

where $k, l, m \in \{+1, -1\}$

- We must impose the constraints $J_{klm} \geq 0$ and $\sum_{klm} J_{klm} = 1$

What group should we use?

- We need $\frac{|G|}{|\Omega|} \in \mathbb{Z}$, so look for an 8 element group
- A natural choice is given by the elementary Abelian group $E8 \cong (\mathbb{Z}/2\mathbb{Z})^3$
- We can label each group element with a tuple of three numbers, each either 1 or -1 then

$$g(h, i, j) g(k, l, m) = g(hk, il, jm) \quad (15)$$

- The group action on Ω is similar

$$g(h, i, j) \cdot (k, l, m) = (hk, il, jm) \quad (16)$$

- It is easy to verify that the following assignments give a projective representation of E_8 with the required properties

$$U_{g(+,+,+)} = I \qquad U_{g(-,-,-)} = \Gamma \qquad (17)$$

$$U_{g(+,-,-)} = X \qquad U_{g(-,+,+)} = \Gamma X \qquad (18)$$

$$U_{g(-,+,-)} = Y \qquad U_{g(+,-,+)} = \Gamma Y \qquad (19)$$

$$U_{g(-,-,+)} = Z \qquad U_{g(+,+, -)} = \Gamma Z \qquad (20)$$

- Γ is an *anti-unitary* operator obeying $\Gamma (I + \vec{r} \cdot \vec{\sigma}) \Gamma^* = I - \vec{r} \cdot \sigma, \forall r \in \mathbb{R}^3$

The main result (1)

- We consider a different group action depending on which marginal we are looking at
- For example, for the first marginal we use $g(k, l, m) \cdot h = kh$, for the second $g(k, l, m) \cdot i = li$, etc.
- These marginal actions obey all the assumptions we need, and the target measurements are covariant so

$$M(A) = A \tag{21}$$

$$M(B) = B \tag{22}$$

$$M(C) = C \tag{23}$$

$$\tag{24}$$

The main result (2)

- In particular

$$d(M(D), A) = d(M(D), M(A)) \quad (25)$$

$$= \|M(D - A)\|_{\text{sup}} \quad (26)$$

$$\leq \|D - A\|_{\text{sup}} \quad (27)$$

$$= d(D, A), \quad (28)$$

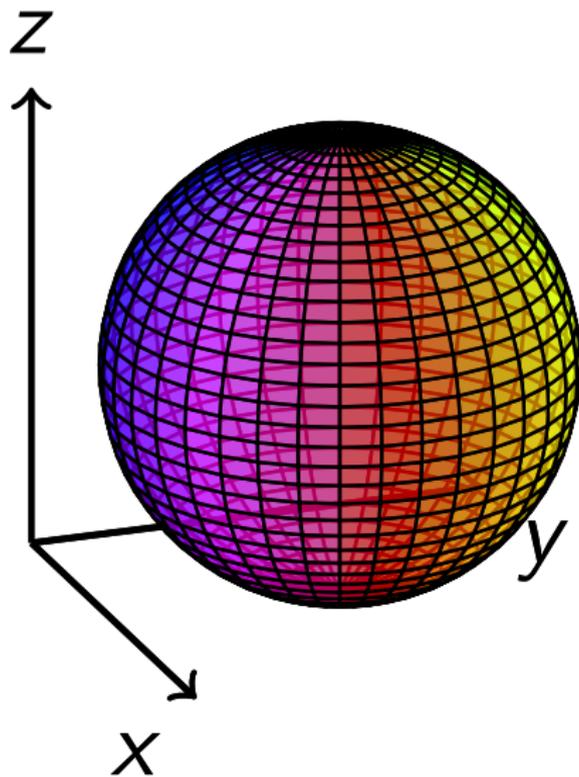
- and similar for the B , E , and C , F pairs
- Applying the map to a joint observable therefore does not increase the error of any of the marginals

The main result (3)

- Covariance fixes the form of J

$$J_{k,l,m} = \frac{1}{8} \left(1 + \begin{pmatrix} k j_x \\ l j_y \\ m j_z \end{pmatrix} \cdot \vec{\sigma} \right) \quad (29)$$

- where j_x , j_y and j_z may be chosen freely as long as $j_x^2 + j_y^2 + j_z^2 \leq 1$
- Computing the marginals then gives $d(D, A) = \frac{1}{2}(1 - j_x)$, and similar for y and z
- The set of allowed $(d(D, A), d(E, B), d(F, C))$ values is therefore a sphere of radius $\frac{1}{2}$, centered at point $\frac{1}{2}$



Thank you for your time
and hopefully your attention!

Covariance of group averaging mapped observable

$$M(E)(\omega) = \frac{1}{|G|} \sum_{g \in G} U_{g^{-1}} E(g.\omega) U_{g^{-1}}^* \quad (30)$$

Let $\tilde{g}h = g$

$$M(E)(\omega) = \frac{1}{|G|} \sum_{\tilde{g} \in G} U_{h^{-1}\tilde{g}^{-1}} E(\tilde{g}h.\omega) U_{h^{-1}\tilde{g}^{-1}}^* \quad (31)$$

$$= U_{h^{-1}} \left(\frac{1}{|G|} \sum_{\tilde{g} \in G} U_{\tilde{g}^{-1}} E(\tilde{g}h.\omega) U_{\tilde{g}^{-1}}^* \right) U_{h^{-1}}^* \quad (32)$$

$$\implies U_h M(E)(\omega) U_h^* = M(E)(h.\omega) \quad (33)$$

M acts to reduce the sup-norm

$$\|M(E)\|_{\text{sup}} = \sup_{\omega} \|M(E)(\omega)\| \quad (34)$$

$$= \sup_{\omega} \left\| \frac{1}{|G|} \sum_{g \in G} U_{g^{-1}} E(g.\omega) U_{g^{-1}}^* \right\| \quad (35)$$

$$\leq \frac{1}{|G|} \sup_{\omega} \sum_{g \in G} \left\| U_{g^{-1}} E(g.\omega) U_{g^{-1}}^* \right\| \quad (36)$$

$$= \frac{1}{|\Omega|} \sup_{\omega} \sum_{\omega' \in \Omega} \|E(\omega')\| \quad (37)$$

$$\leq \sup_{\omega} \|E(\omega)\| \quad (38)$$

$$= \|E\|_{\text{sup}} \quad (39)$$