



Quantum Compilation by Optimal Control of Open Systems: Recent Results & Perspectives for SP4

Thomas Schulte-Herbrüggen,
Andreas Spörl, and Steffen J. Glaser

Technical University Munich, TUM

QAP SP4 Meeting, Maria Laach, March 2007

I. Quantum
Compilation

II. Quantum Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook



SP4: Key Results by TUM 2006/07

I. Quantum
Compilation

II. Quantum Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook

- optimal control of open systems **WP 4.3 & 4.5**
 - Markovian example: encoded CNOT [quant-ph/0609037](#)
 - non-Markovian extension: Z-gate [quant-ph/0612165](#)
- control of coupled Josephson charge qubits **WP 4.3**
 - 100-fold less error for CNOT & TOFFOLI [PRA 75 012302 \(2007\)](#)
- local time-reversal, local optimisation **WP 4.5**
 - details in [quant-ph/0610061](#), [math-ph/0701035](#), [math-ph/0702005](#)
- parallelising GRAPE **WP 4.3, 4.4, 4.5**
 - 500-fold speed-up on parallel cluster [LNCS 4128, 751 \(2006\)](#)



SP4: Key Results by TUM 2006/07

I. Quantum
Compilation

II. Quantum Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook

- optimal control of open systems **WP 4.3 & 4.5**
 - Markovian example: encoded CNOT [quant-ph/0609037](#)
 - non-Markovian extension: Z -gate [quant-ph/0612165](#)
- control of coupled Josephson charge qubits **WP 4.3**
 - 100-fold less error for CNOT & TOFFOLI [PRA 75 012302 \(2007\)](#)
- local time-reversal, local optimisation **WP 4.5**
 - details in [quant-ph/0610061](#), [math-ph/0701035](#), [math-ph/0702005](#)
- parallelising GRAPE **WP 4.3, 4.4, 4.5**
 - 500-fold speed-up on parallel cluster [LNCS 4128, 751 \(2006\)](#)



SP4: Key Results by TUM 2006/07

I. Quantum
Compilation

II. Quantum Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook

- optimal control of open systems **WP 4.3 & 4.5**
 - Markovian example: encoded CNOT [quant-ph/0609037](https://arxiv.org/abs/quant-ph/0609037)
 - non-Markovian extension: Z -gate [quant-ph/0612165](https://arxiv.org/abs/quant-ph/0612165)
- control of coupled Josephson charge qubits **WP 4.3**
 - 100-fold less error for CNOT & TOFFOLI [PRA 75 012302 \(2007\)](https://arxiv.org/abs/quant-ph/0612165)
- local time-reversal, local optimisation **WP 4.5**
 - details in [quant-ph/0610061](https://arxiv.org/abs/quant-ph/0610061), [math-ph/0701035](https://arxiv.org/abs/math-ph/0701035), [math-ph/0702005](https://arxiv.org/abs/math-ph/0702005)
- parallelising GRAPE **WP 4.3, 4.4, 4.5**
 - 500-fold speed-up on parallel cluster [LNCS 4128, 751 \(2006\)](https://arxiv.org/abs/quant-ph/0612165)



SP4: Key Results by TUM 2006/07

I. Quantum
Compilation

II. Quantum Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook

- optimal control of open systems **WP 4.3 & 4.5**
 - Markovian example: encoded CNOT [quant-ph/0609037](https://arxiv.org/abs/quant-ph/0609037)
 - non-Markovian extension: Z -gate [quant-ph/0612165](https://arxiv.org/abs/quant-ph/0612165)
- control of coupled Josephson charge qubits **WP 4.3**
 - 100-fold less error for CNOT & TOFFOLI [PRA 75 012302 \(2007\)](https://arxiv.org/abs/physics/0701230)
- local time-reversal, local optimisation **WP 4.5**
 - details in [quant-ph/0610061](https://arxiv.org/abs/quant-ph/0610061), [math-ph/0701035](https://arxiv.org/abs/math-ph/0701035), [math-ph/0702005](https://arxiv.org/abs/math-ph/0702005)
- parallelising GRAPE **WP 4.3, 4.4, 4.5**
 - 500-fold speed-up on parallel cluster [LNCS 4128, 751 \(2006\)](https://arxiv.org/abs/quant-ph/0604128)

Motivation: Control in Quantum Technology

*We are currently in the midst of a **second quantum revolution**. The first quantum revolution gave us new rules that govern physical reality. The second quantum revolution will take these rules and use them to develop **new technologies**.* DOWLING & MILBURN, 2003

I. Quantum
Compilation

II. Quantum Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

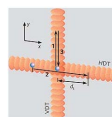
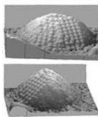
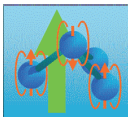
Conclusions &
Outlook

■ economy

currently some 30% of the GNP of industrial states depend on quantum effects (transistor, laser)

■ technology ahead

quantum & nano-technology rely on **quantum control**
(solid-state devices, spintronics–NMR–EPR, quantum dots, ion-traps)



Motivation: Control in Quantum Technology

*We are currently in the midst of a **second quantum revolution**. The first quantum revolution gave us new rules that govern physical reality. The second quantum revolution will take these rules and use them to develop **new technologies**.* DOWLING & MILBURN, 2003

I. Quantum
Compilation

II. Quantum Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

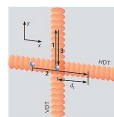
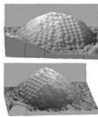
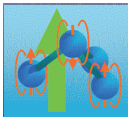
Conclusions &
Outlook

- economy

currently some 30% of the GNP of industrial states depend on quantum effects (transistor, laser)

- technology ahead

quantum & nano-technology rely on **quantum control**
(solid-state devices, spintronics–NMR–EPR, quantum dots, ion-traps)





Classical Compiler

Compilation into Machine Code

I. Quantum
Compilation

II. Quantum Control

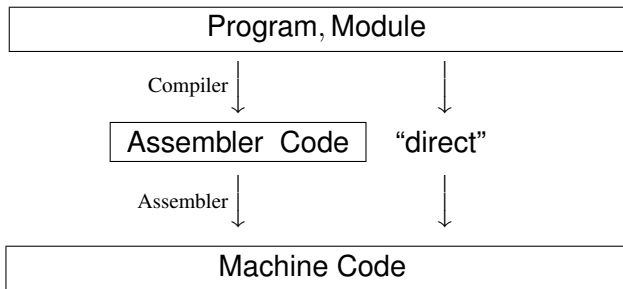
SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook

■ Classical Compilation





Quantum Compiler

Compilation into Machine Code of Quantum Controls

I. Quantum
Compilation

II. Quantum Control

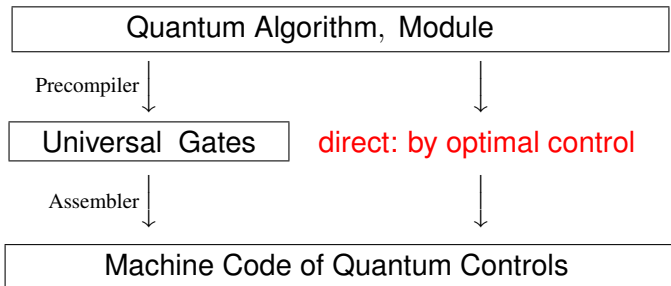
SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook

■ Quantum Compilation: a Control Problem



NB crucial for quantum machine code:
has to be timeoptimal or decoherence protected



Quantum Compiler

Compilation into Machine Code of Quantum Controls

I. Quantum
Compilation

II. Quantum Control

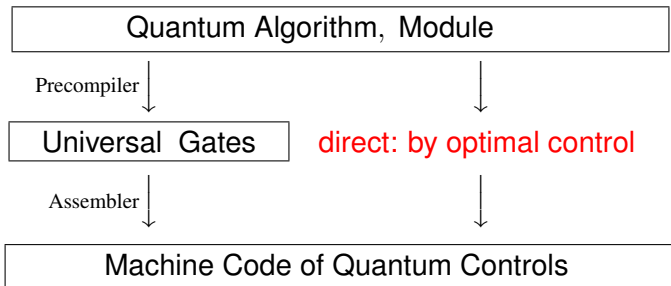
SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook

■ Quantum Compilation: a Control Problem



NB **crucial** for **quantum** machine code:
has to be **timeoptimal** or **decoherence protected**



Outline

- 1 Quantum Compiler
- 2 Quantum Control
 - Optimisation within Unitary Group ($PSU(N)$)
 - Optimisation under Dissipation
- 3 SP4: Dissemination of GRAPE Package
- 4 SP4: Perspectives of Common Goals
- 5 Local Control
 - Local Numerical Ranges
 - Local Gradient Flows
 - Pure-State Entanglement
 - Local Timereversal
- 6 Conclusions & Outlook

I. Quantum
Compilation

II. Quantum Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook



■ Bilinear Control System

$$\dot{X}(t) = \left(A + \sum_{j=1}^m u_j(t) B_j \right) X(t)$$

■ Hamiltonian dynamics (Schrödinger equation)

$$|\dot{\psi}(t)\rangle = -i \left(H_d + \sum_{j=1}^m u_j(t) H_j \right) |\psi(t)\rangle$$

- H_d : drift term
- H_j : controls
- $u_j(t)$: control amplitudes



Control of Hamiltonian Dynamics

I. Quantum
Compilation

II. Quantum Control

Optimising on $PSU(N)$
Decoherence Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook

■ Bilinear Control System

$$\dot{X}(t) = \left(A + \sum_{j=1}^m u_j(t) B_j \right) X(t)$$

■ Hamiltonian dynamics (Schrödinger equation)

$$|\dot{\psi}(t)\rangle = -i \left(H_d + \sum_{j=1}^m u_j(t) H_j \right) |\psi(t)\rangle$$

- H_d : drift term
- H_j : controls
- $u_j(t)$: control amplitudes



Controllability of Quantum Systems

In systems of n qubits:

$$|\dot{\psi}(t)\rangle = -i(H_d + \sum_{j=1}^m u_j(t)H_j) |\psi(t)\rangle \in \mathbb{C}^{2^n} \quad (1)$$

where $|\psi\rangle \in \mathbb{C}^{2^n}$ and $iH_j \in \mathfrak{su}(2^n)$.

Definition

A system is **fully controllable**, if every state on the unitary orbit can be reached (in finite time). For normal A, C this means every final state $X(t) =: C$ can be reached from any initial state $X(0) =: A$ with the same spectrum.

Corollary

The bilinear system (1) is **fully controllable** if drift and controls are a generating set of $\mathfrak{su}(2^n)$ by way of commutation, i.e. $\langle H_d, H_j \mid j = 1, 2, \dots, m \rangle_{\text{Lie}} \stackrel{\text{iso}}{=} \mathfrak{su}(2^n)$.

I. Quantum
Compilation

II. Quantum Control

Optimising on $PSU(N)$
Decoherence Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook



Controllability of Quantum Systems

In systems of n qubits:

$$|\dot{\psi}(t)\rangle = -i(H_d + \sum_{j=1}^m u_j(t)H_j) |\psi(t)\rangle \in \mathbb{C}^{2^n} \quad (1)$$

where $|\psi\rangle \in \mathbb{C}^{2^n}$ and $iH_j \in \mathfrak{su}(2^n)$.

Definition

A system is **fully controllable**, if every state on the unitary orbit can be reached (in finite time). For normal A, C this means every final state $X(t) =: C$ can be reached from any initial state $X(0) =: A$ with the same spectrum.

Corollary

The bilinear system (1) is **fully controllable** if drift and controls are a generating set of $\mathfrak{su}(2^n)$ by way of commutation, i.e. $\langle H_d, H_j \mid j = 1, 2, \dots, m \rangle_{\text{Lie}} \stackrel{\text{iso}}{=} \mathfrak{su}(2^n)$.

I. Quantum
Compilation

II. Quantum Control

Optimising on $PSU(N)$
Decoherence Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook



Controllability and Coupling Topology

- Example: n weakly coupled spins- $\frac{1}{2}$.

Which conditions suffice for

$$\langle H_d, H_j \mid j = 1, 2, \dots, m \rangle_{\text{Lie}} \stackrel{\text{iso}}{=} \mathfrak{su}(2^n) ?$$

Lemma (Diss-ETH 12752)

A system of n qubits is **fully controllable**, if e.g. the control Hamiltonians H_j comprise $\{\sigma_{kx}, \sigma_{ky} \mid k = 1, 2, \dots, n\}$ on every single qubit selectively and the drift Hamiltonian H_d encompasses the Ising pair interactions $\{J_{kl} (\sigma_{kz} \otimes \sigma_{lz})/2 \mid k < l = 2, \dots, n\}$, where the coupling topology of $J_{kl} \neq 0$ may take the form of **any connected graph**.

I. Quantum Compilation

II. Quantum Control

Optimising on $PSU(N)$

Decoherence Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions & Outlook



Controllability and Quantum Gates

I. Quantum
Compilation

II. Quantum Control

Optimising on $PSU(N)$
Decoherence Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook

Corollary

The following are equivalent:

- 1 *in a quantum system drift H_d and controls H_j form a generating set of $\mathfrak{su}(2^n)$;*
- 2 *every unitary transformation in $SU(2^n)$ can be realised on that quantum hardware;*
- 3 *there is a set of **universal quantum gates** for the quantum system;*



Controllability and Quantum Gates

I. Quantum
Compilation

II. Quantum Control

Optimising on $PSU(N)$
Decoherence Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook

Corollary

The following are equivalent:

- 1** *in a quantum system drift H_d and controls H_j form a generating set of $\mathfrak{su}(2^n)$;*
- 2** *every unitary transformation in $SU(2^n)$ can be realised on that quantum hardware;*
- 3** *there is a set of **universal quantum gates** for the quantum system;*



Controllability and Quantum Gates

I. Quantum
Compilation

II. Quantum Control

Optimising on $PSU(N)$
Decoherence Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook

Corollary

The following are equivalent:

- 1** *in a quantum system drift H_d and controls H_j form a generating set of $\mathfrak{su}(2^n)$;*
- 2** *every unitary transformation in $SU(2^n)$ can be realised on that quantum hardware;*
- 3** *there is a set of **universal quantum gates** for the quantum system;*



Controllability and Quantum Gates

I. Quantum
Compilation

II. Quantum Control

Optimising on $PSU(N)$
Decoherence Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook

Corollary

The following are equivalent:

- 1 *in a quantum system drift H_d and controls H_j form a generating set of $\mathfrak{su}(2^n)$;*
- 2 *every unitary transformation in $SU(2^n)$ can be realised on that quantum hardware;*
- 3 *there is a set of **universal quantum gates** for the quantum system;*



Principles: Optimal Quantum Control

I. Quantum
Compilation

II. Quantum Control

Optimising on $PSU(N)$
Decoherence Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook

Scope in Optimal Control:

maximise quality function **subject to** equation of motion

Scenarios:

■ Hamiltonian dynamics

notation: $U := e^{-itH}$; $\text{Ad}_U(\cdot) := U(\cdot)U^{-1}$; $\text{ad}_H(\cdot) := [H, \cdot]$

1. pure state $|\dot{\psi}\rangle = -iH |\psi\rangle \in \mathcal{H}$
2. gate $\dot{U} = -iH U \in \mathcal{U}(\mathcal{H})$
3. non-pure state $\dot{\rho} = -i \text{ad}_H(\rho) \in \mathcal{B}_1(\mathcal{H})$
4. projective gate $\dot{\text{Ad}}_U = -i \text{ad}_H \circ \text{Ad}_U \in \mathcal{U}(\mathcal{B}_1(\mathcal{H}))$

■ Master equations of dissipative dynamics

- 3'. non-pure state $\dot{\rho} = -(i \text{ad}_H + \Gamma)(\rho)$
- 4'. **contractive** map $\dot{\chi} = -(i \text{ad}_H + \Gamma) \circ \chi \in \mathcal{GL}(\mathcal{B}_1(\mathcal{H}))$



Principles: Optimal Quantum Control

I. Quantum
Compilation

II. Quantum Control

Optimising on $PSU(N)$
Decoherence Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook

Scope in Optimal Control:

maximise quality function **subject to** equation of motion

Scenarios:

■ Hamiltonian dynamics

notation: $U := e^{-itH}$; $\text{Ad}_U(\cdot) := U(\cdot)U^{-1}$; $\text{ad}_H(\cdot) := [H, \cdot]$

1. pure state $|\dot{\psi}\rangle = -iH |\psi\rangle \in \mathcal{H}$
2. gate $\dot{U} = -iH U \in \mathcal{U}(\mathcal{H})$
3. non-pure state $\dot{\rho} = -i \text{ad}_H(\rho) \in \mathcal{B}_1(\mathcal{H})$
4. projective gate $\dot{\text{Ad}}_U = -i \text{ad}_H \circ \text{Ad}_U \in \mathcal{U}(\mathcal{B}_1(\mathcal{H}))$

■ Master equations of dissipative dynamics

- 3'. non-pure state $\dot{\rho} = -(i \text{ad}_H + \Gamma)(\rho)$
- 4'. **contractive** map $\dot{\chi} = -(i \text{ad}_H + \Gamma) \circ \chi \in \mathcal{GL}(\mathcal{B}_1(\mathcal{H}))$



Typical Tasks in Optimal Quantum Control

I. Quantum
Compilation

II. Quantum Control

Optimising on $PSU(N)$
Decoherence Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook

1. Maximising Experimental Sensitivity:

maximise transfer amplitude $f := |\text{tr}\{C^\dagger UAU^\dagger\}|$,
subject to equation of motion $\dot{A} = -i[H, A]$

Glaser, T.S.H., Sieveking, Schedletzky, Nielsen, Sørensen, Griesinger,
Science **280** (1998), 421

2. Realise Quantum Gate U_G in Minimal Time:

maximise fidelity $\text{Re tr}\{\text{Ad}_{U_G}^\dagger \text{Ad}_U(T)\}$
subject to equation of motion

$$\dot{\text{Ad}}_U(t) = -i \text{ad}_H \circ \text{Ad}_U(t)$$

T.S.H., Spörl, Khaneja, Glaser, *Phys. Rev. A* **72** (2005), 042331

3. Realise Module U_G with Minimal Relaxative Loss:

maximise fidelity $\text{Re tr}\{\text{Ad}_{U_G}^\dagger \chi(T)\}$
subject to equation of motion (now Master Equation)

$$\dot{\chi}(t) = -(i \text{ad}_H + \Gamma) \circ \chi(t)$$

quant-ph/0609037



Typical Tasks in Optimal Quantum Control

I. Quantum
Compilation

II. Quantum Control

Optimising on $PSU(N)$
Decoherence Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook

1. Maximising Experimental Sensitivity:

maximise transfer amplitude $f := |\text{tr}\{C^\dagger UAU^\dagger\}|$,
subject to equation of motion $\dot{A} = -i[H, A]$

Glaser, T.S.H., Sieveking, Schedletsky, Nielsen, Sørensen, Griesinger,
Science **280** (1998), 421

2. Realise Quantum Gate U_G in Minimal Time:

maximise fidelity $\text{Re tr}\{\text{Ad}_{U_G}^\dagger \text{Ad}_U(T)\}$
subject to equation of motion
 $\text{Ad}_U(t) = -i \text{ad}_H \circ \text{Ad}_U(t)$

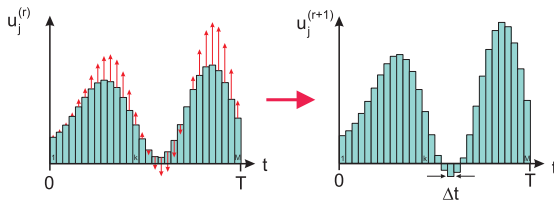
T.S.H., Spörl, Khaneja, Glaser, *Phys. Rev. A* **72** (2005), 042331

3. Realise Module U_G with Minimal Relaxative Loss:

maximise fidelity $\text{Re tr}\{\text{Ad}_{U_G}^\dagger \chi(T)\}$
subject to equation of motion (now Master Equation)
 $\dot{\chi}(t) = -(i \text{ad}_H + \Gamma) \circ \chi(t)$

quant-ph/0609037

■ Gradient Ascent Algorithm GRAPE



J. Magn. Reson. **172** (2005), 296 and *Phys. Rev. A* **72** (2005), 042331

Generation of Unitary Operators

$$U(0) = 1$$
$$\dot{U} = -i H U$$
$$U(T)$$

I. Quantum
Compilation

II. Quantum Control

Optimising on $PSU(N)$

Decoherence Control

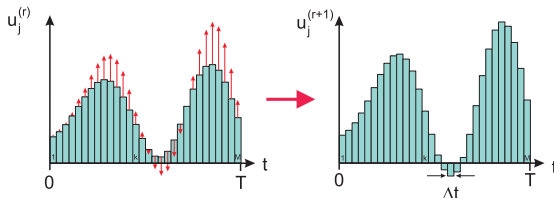
SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook

■ Gradient Ascent Algorithm GRAPE



- 1 Define scalar-valued HAMILTON function

$$h(U) = \text{Re tr}\{\lambda^\dagger(-i(H_d + \sum_j u_j H_j))U\}$$

- 2 with adjoint system satisfying

$$\dot{\lambda}(t) = -i(H_d + \sum_j u_j H_j)\lambda(t) \quad .$$

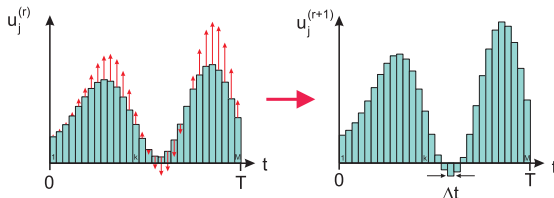
- 3 Then PONTYAGIN's maximum principle requires

$$\frac{\partial h}{\partial u_j} = \text{Re tr}\{\lambda^\dagger(-iH_j)U\} \stackrel{!}{=} 0$$

- 4 thus allowing for a **gradient-flow of quantum controls**

$$u_j(t_k^{(r+1)}) = u_j(t_k^{(r)}) + \varepsilon \frac{\partial h}{\partial u_j} \Big|_{t=t_k} \quad .$$

■ Gradient Ascent Algorithm GRAPE



- 1 Define scalar-valued HAMILTON function

$$h(U) = \text{Re tr}\{\lambda^\dagger(-i(H_d + \sum_j u_j H_j))U\}$$

- 2 with adjoint system satisfying

$$\dot{\lambda}(t) = -i(H_d + \sum_j u_j H_j)\lambda(t)$$

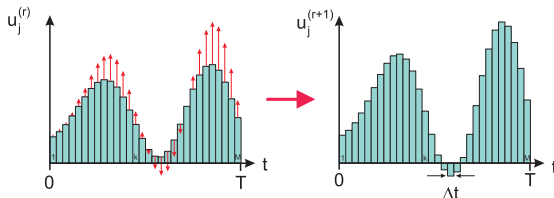
- 3 Then PONTYAGIN's maximum principle requires

$$\frac{\partial h}{\partial u_j} = \text{Re tr}\{\lambda^\dagger(-iH_j)U\} \stackrel{!}{=} 0$$

- 4 thus allowing for a gradient-flow of quantum controls

$$u_j(t_k^{(r+1)}) = u_j(t_k^{(r)}) + \varepsilon \frac{\partial h}{\partial u_j} \Big|_{t=t_k}$$

■ Gradient Ascent Algorithm GRAPE



- 1 Define scalar-valued HAMILTON function

$$h(U) = \text{Re tr}\{\lambda^\dagger(-i(H_d + \sum_j u_j H_j))U\}$$

- 2 with adjoint system satisfying

$$\dot{\lambda}(t) = -i(H_d + \sum_j u_j H_j)\lambda(t) \quad .$$

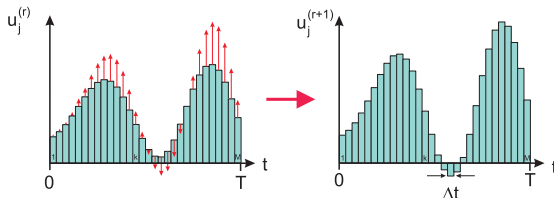
- 3 Then PONTYAGIN's maximum principle requires

$$\frac{\partial h}{\partial u_j} = \text{Re tr}\{\lambda^\dagger(-iH_j)U\} \stackrel{!}{=} 0$$

- 4 thus allowing for a gradient-flow of quantum controls

$$u_j(t_k^{(r+1)}) = u_j(t_k^{(r)}) + \varepsilon \frac{\partial h}{\partial u_j} \Big|_{t=t_k} \quad .$$

■ Gradient Ascent Algorithm GRAPE



- 1 Define scalar-valued HAMILTON function

$$h(U) = \text{Re tr}\{\lambda^\dagger(-i(H_d + \sum_j u_j H_j))U\}$$

- 2 with adjoint system satisfying

$$\dot{\lambda}(t) = -i(H_d + \sum_j u_j H_j)\lambda(t) \quad .$$

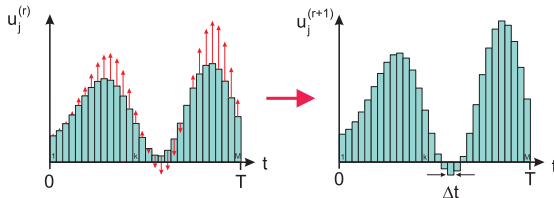
- 3 Then PONTYAGIN's maximum principle requires

$$\frac{\partial h}{\partial u_j} = \text{Re tr}\{\lambda^\dagger(-iH_j)U\} \stackrel{!}{=} 0$$

- 4 thus allowing for a gradient-flow of quantum controls

$$u_j(t_k^{(r+1)}) = u_j(t_k^{(r)}) + \varepsilon \frac{\partial h}{\partial u_j} \Big|_{t=t_k}$$

■ Gradient Ascent Algorithm GRAPE



- 1 Define scalar-valued HAMILTON function

$$h(U) = \text{Re tr}\{\lambda^\dagger(-i(H_d + \sum_j u_j H_j))U\}$$

- 2 with adjoint system satisfying

$$\dot{\lambda}(t) = -i(H_d + \sum_j u_j H_j)\lambda(t) \quad .$$

- 3 Then PONTYAGIN's maximum principle requires

$$\frac{\partial h}{\partial u_j} = \text{Re tr}\{\lambda^\dagger(-iH_j)U\} \stackrel{!}{=} 0$$

- 4 thus allowing for a **gradient-flow of quantum controls**

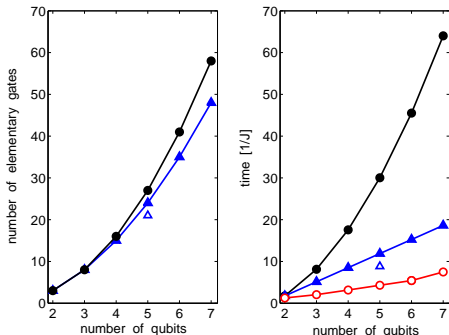
$$u_j(t_k^{(r+1)}) = u_j(t_k^{(r)}) + \varepsilon \frac{\partial h}{\partial u_j} \Big|_{t=t_k}$$

Examples of Quantum Control

2. Realising Quantum Gates in Minimal Time

Goal: *time complexity* of QFT on linear spin chain for

- Shor's algorithm
- all algorithms of (abelian) *hidden subgroup* type



⇒ timeopt. QFT: **some 3 times faster** than fastest current standard-gate decompositions

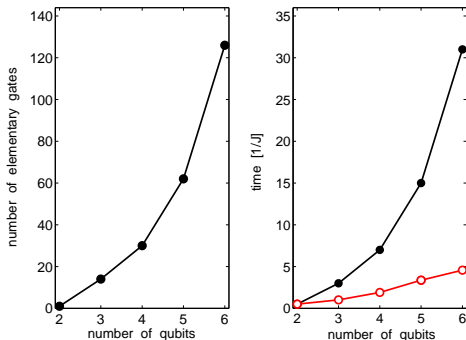


Examples of Quantum Control

2. Realising Quantum Gates in Minimal Time

Goal: *time complexity* of C^n NOT as module in

- Quantum Error Correction



⇒ timeopt. C^n NOT: **quadratically faster** than fastest current standard-gate decomposition

I. Quantum
Compilation

II. Quantum Control

Optimising on $PSU(N)$

Decoherence Control

SP4: Dissemination

SP4: Perspectives

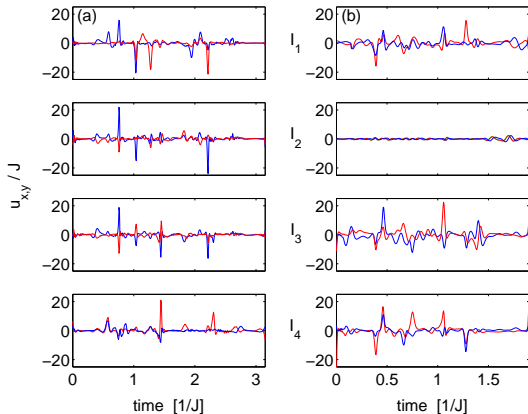
III. Local Control

Conclusions &
Outlook

Examples of Quantum Control

2. Realising Quantum Gates in Minimal Time

■ How do 'optimal controls' look like?



⇒ often difficult to understand!



I. Quantum
Compilation

II. Quantum Control

Optimising on $PSU(N)$

Decoherence Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook



Examples of Quantum Control

2. Realising Quantum Gates in Minimal Time with F. Wilhelm, M. Storcz

Goal: realise *timeoptimal* CNOT on 2 coupled charge qubits

- pseudospin Hamiltonian: $H = H_{\text{drift}}$

$$\begin{aligned} H_{\text{drift}} = & - \left(\frac{E_m}{4} + \frac{E_{c1}}{2} \right) (\sigma_z^{(1)} \otimes \mathbf{1}) - \frac{E_{J1}}{2} (\sigma_x^{(1)} \otimes \mathbf{1}) \\ & - \left(\frac{E_m}{4} + \frac{E_{c2}}{2} \right) (\mathbf{1} \otimes \sigma_z^{(2)}) - \frac{E_{J2}}{2} (\mathbf{1} \otimes \sigma_x^{(2)}) \\ & + \frac{E_m}{4} (\sigma_z^{(1)} \otimes \sigma_z^{(2)}) \end{aligned}$$

I. Quantum
Compilation

II. Quantum Control

Optimising on $PSU(N)$

Decoherence Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook



Examples of Quantum Control

2. Realising Quantum Gates in Minimal Time with F. Wilhelm, M. Storcz

Goal: realise *timeoptimal* CNOT on 2 coupled charge qubits

■ pseudospin Hamiltonian: $H = H_{\text{drift}} + H_{\text{control}}$

$$\begin{aligned} H_{\text{drift}} = & - \left(\frac{E_m}{4} + \frac{E_{c1}}{2} \right) (\sigma_z^{(1)} \otimes \mathbf{1}) - \frac{E_{J1}}{2} (\sigma_x^{(1)} \otimes \mathbf{1}) \\ & - \left(\frac{E_m}{4} + \frac{E_{c2}}{2} \right) (\mathbf{1} \otimes \sigma_z^{(2)}) - \frac{E_{J2}}{2} (\mathbf{1} \otimes \sigma_x^{(2)}) \\ & + \frac{E_m}{4} (\sigma_z^{(1)} \otimes \sigma_z^{(2)}) \end{aligned}$$

$$\begin{aligned} H_{\text{control}} = & \left(\frac{E_m}{2} n_{g2} + E_{c1} n_{g1} \right) (\sigma_z^{(1)} \otimes \mathbf{1}) \\ & + \left(\frac{E_m}{2} n_{g1} + E_{c2} n_{g2} \right) (\mathbf{1} \otimes \sigma_z^{(2)}) \end{aligned}$$

NB: components of $\{H_d, H_d, H_c\}$ form minimal generating set of $\mathfrak{su}(4)$.

I. Quantum
Compilation

II. Quantum Control

Optimising on $PSU(N)$

Decoherence Control

SP4: Dissemination

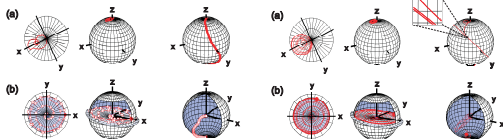
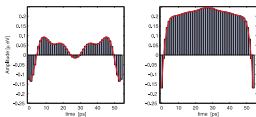
SP4: Perspectives

III. Local Control

Conclusions &
Outlook

Examples of Quantum Control

2. Realising Quantum Gates in Minimal Time



⇒ timeopt. CNOT: **some 5 times faster** than NEC group

- Quality $q := Fe^{-\tau_{\text{op}}/\tau_Q}$

so $1 - q = 1 - 0.999999999 e^{-55\text{ps}/10\text{ns}} = \mathbf{0.0055}$

(NEC: $1 - q = 1 - 0.4188 e^{-250\text{ps}/10\text{ns}} = 0.5917$)

PRA 75, 012302 (2007)

I. Quantum
Compilation

II. Quantum Control

Optimising on $PSU(N)$

Decoherence Control

SP4: Dissemination

SP4: Perspectives

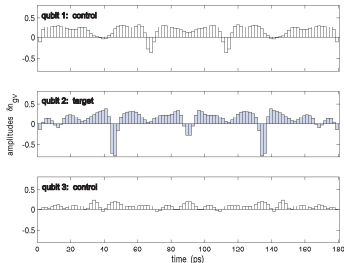
III. Local Control

Conclusions &
Outlook

Examples of Quantum Control

2. Realising Quantum Gates in Minimal Time

Goal: TOFFOLI gate on 3 linearly coupled charge qubits



13 times faster than NEC

■ error rates cut by two orders of magnitude ($T_2 \simeq 10$ ns):

1 direct gate by optimal control

$$1 - q = 1 - 0.99999 e^{-180\text{ps}/10\text{ns}} = 0.0178$$

2 by 9 CNOT's from optimal control

$$1 - q = 1 - (0.999999999 e^{-55\text{ps}/10\text{ns}})^9 = 0.0483$$

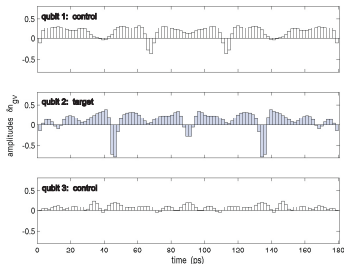
3 by 9 CNOT's under pioneering controls

$$1 - q = 1 - (0.4188 e^{-250\text{ps}/10\text{ns}})^9 = 0.9997$$

Examples of Quantum Control

2. Realising Quantum Gates in Minimal Time

Goal: TOFFOLI gate on 3 linearly coupled charge qubits



13 times faster than NEC

■ error rates cut by two orders of magnitude ($T_2 \simeq 10$ ns):

1 direct gate by optimal control

$$1 - q = 1 - 0.99999 e^{-180\text{ps}/10\text{ns}} = 0.0178$$

2 by 9 CNOT's from optimal control

$$1 - q = 1 - (0.999999999 e^{-55\text{ps}/10\text{ns}})^9 = 0.0483$$

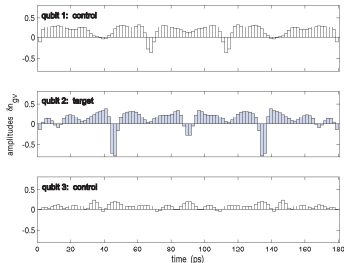
3 by 9 CNOT's under pioneering controls

$$1 - q = 1 - (0.4188 e^{-250\text{ps}/10\text{ns}})^9 = 0.9997$$

Examples of Quantum Control

2. Realising Quantum Gates in Minimal Time

Goal: TOFFOLI gate on 3 linearly coupled charge qubits



13 times faster than NEC

■ error rates cut by **two orders of magnitude** ($T_2 \simeq 10$ ns):

1 direct gate by optimal control

$$1 - q = 1 - 0.99999 e^{-180\text{ps}/10\text{ns}} = \mathbf{0.0178}$$

2 by 9 CNOT's from optimal control

$$1 - q = 1 - (0.999999999 e^{-55\text{ps}/10\text{ns}})^9 = 0.0483$$

3 by 9 CNOT's under pioneering controls

$$1 - q = 1 - (0.4188 e^{-250\text{ps}/10\text{ns}})^9 = \mathbf{0.9997}$$

I. Quantum
Compilation

II. Quantum Control

Optimising on $PSU(N)$

Decoherence Control

SP4: Dissemination

SP4: Perspectives

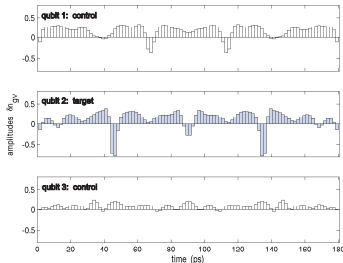
III. Local Control

Conclusions &
Outlook

Examples of Quantum Control

2. Realising Quantum Gates in Minimal Time

Goal: TOFFOLI gate on 3 linearly coupled charge qubits



13 times faster than NEC

■ error rates cut by **two orders of magnitude** ($T_2 \simeq 10$ ns):

1 direct gate by optimal control

$$1 - q = 1 - 0.99999 e^{-180\text{ps}/10\text{ns}} = \mathbf{0.0178}$$

2 by 9 CNOT's from optimal control

$$1 - q = 1 - (0.999999999 e^{-55\text{ps}/10\text{ns}})^9 = 0.0483$$

3 by 9 CNOT's under pioneering controls

$$1 - q = 1 - (0.4188 e^{-250\text{ps}/10\text{ns}})^9 = \mathbf{0.9997}$$

I. Quantum
Compilation

II. Quantum Control

Optimising on $PSU(N)$

Decoherence Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook



Quantum Compiler

Compilation into Machine Code of Quantum Controls

I. Quantum
Compilation

II. Quantum Control

Optimising on $PSU(N)$

Decoherence Control

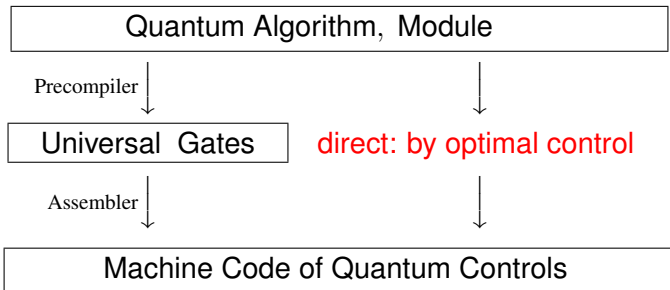
SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook

- Challenge in Quantum Compilation:
fight decoherence by (i) timeoptimal or (ii)
decoherence-protected controls!





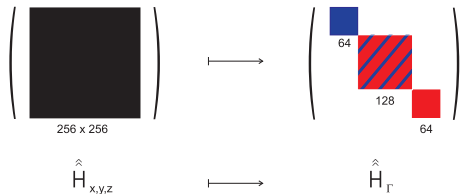
Examples of Quantum Control

3. Idea of Decoherence-Free Subspaces (DFS)

Principle:

Code logical qubits in decoherence-free *physical* levels

- Master equation: $\dot{\rho} = -(i \text{ad}_H + \Gamma) \rho$
- **DFS**: eigenspace to Γ with **eigenvalue = 0**
- Express $\hat{H} \equiv \text{ad}_H$ in eigenbasis of Γ (here 4 qubits)



- Idea: perform calculation (e.g. CNOT) **within DFS**

Zanardi, Rasetti, *Phys. Rev. Lett.* **79** (1997), 3309.

Lidar, Chuang, Whaley, *Phys. Rev. Lett.* **81** (1998), 2594.



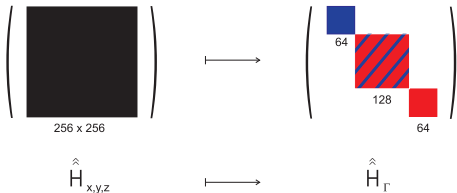
Examples of Quantum Control

3. Idea of Decoherence-Free Subspaces (DFS)

Principle:

Code logical qubits in decoherence-free *physical* levels

- Master equation: $\dot{\rho} = -(i \text{ad}_H + \Gamma) \rho$
- **DFS**: eigenspace to Γ with **eigenvalue = 0**
- Express $\hat{H} \equiv \text{ad}_H$ in eigenbasis of Γ (here 4 qubits)



- Idea: perform calculation (e.g. CNOT) **within DFS**

Zanardi, Rasetti, *Phys. Rev. Lett.* **79** (1997), 3309.

Lidar, Chuang, Whaley, *Phys. Rev. Lett.* **81** (1998), 2594.



Examples of Quantum Control

3. Model System: 2 Qubits by 4 Spins

- 1 logical qubit coded by 2 physical qubits in Bell states

$$|0\rangle_L := |\psi^+\rangle = \frac{1}{\sqrt{2}}(|01\rangle + |10\rangle), \quad |1\rangle_L := |\psi^-\rangle = \frac{1}{\sqrt{2}}(|01\rangle - |10\rangle)$$

$$\mathcal{B} := \text{span} \{ |\psi^\pm\rangle\langle\psi^\pm|, |\psi^\mp\rangle\langle\psi^\pm| \}$$

I. Quantum
Compilation

II. Quantum Control

Optimising on $PSU(N)$

Decoherence Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook



Examples of Quantum Control

3. Model System: 2 Qubits by 4 Spins

- 1 logical qubit coded by 2 physical qubits in Bell states

$$|0\rangle_L := |\psi^+\rangle = \frac{1}{\sqrt{2}}(|01\rangle + |10\rangle), \quad |1\rangle_L := |\psi^-\rangle = \frac{1}{\sqrt{2}}(|01\rangle - |10\rangle)$$

$$\mathcal{B} := \text{span} \{ |\psi^\pm\rangle\langle\psi^\pm|, |\psi^\mp\rangle\langle\psi^\pm| \}$$

- 2 logical qubits coded by 4 physical qubits

$$\begin{array}{c} \bullet \text{---} \frac{1}{\sqrt{2}}(|01\rangle + |10\rangle) \\ \frac{1}{\sqrt{2}}(|01\rangle - |10\rangle) \text{---} \bullet \end{array}$$

$$\begin{array}{c} \bullet \text{---} \frac{1}{\sqrt{2}}(|01\rangle + |10\rangle) \\ \frac{1}{\sqrt{2}}(|01\rangle - |10\rangle) \text{---} \bullet \end{array}$$

I. Quantum
Compilation

II. Quantum Control

Optimising on $PSU(N)$

Decoherence Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook



Examples of Quantum Control

3. Model System: 2 Qubits by 4 Spins

I. Quantum
Compilation

II. Quantum Control

Optimising on $PSU(N)$

Decoherence Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook

- 1 logical qubit coded by 2 physical qubits in Bell states

$$|0\rangle_L := |\psi^+\rangle = \frac{1}{\sqrt{2}}(|01\rangle + |10\rangle), \quad |1\rangle_L := |\psi^-\rangle = \frac{1}{\sqrt{2}}(|01\rangle - |10\rangle)$$

$$\mathcal{B} := \text{span} \{ |\psi^\pm\rangle\langle\psi^\pm|, |\psi^\mp\rangle\langle\psi^\pm| \}$$

- 2 logical qubits coded by 4 physical qubits

$$\begin{array}{c} \bullet \text{---} \frac{1}{\sqrt{2}}(|01\rangle + |10\rangle) \text{---} \bullet \\ \frac{1}{\sqrt{2}}(|01\rangle - |10\rangle) \end{array}$$

$$\begin{array}{c} \bullet \text{---} \frac{1}{\sqrt{2}}(|01\rangle + |10\rangle) \text{---} \bullet \\ \frac{1}{\sqrt{2}}(|01\rangle - |10\rangle) \end{array}$$

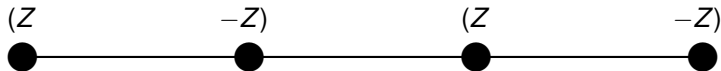
- protection against T_2 relaxation (Redfield: $\Gamma \sim [ZZ, [ZZ, \rho]]$)

because $[\rho, ZZ] = 0 \quad \forall \quad \rho \in \mathcal{B} \otimes \mathcal{B}$

Examples of Quantum Control

3. Model Systems: 4 Linearly Coupled Spins

■ controls



I. Quantum
Compilation

II. Quantum Control

Optimising on $PSU(N)$

Decoherence Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

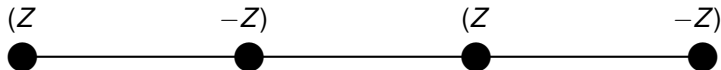
Conclusions &
Outlook



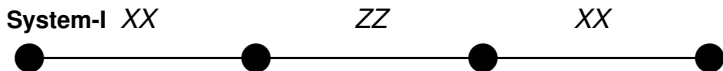
Examples of Quantum Control

3. Model Systems: 4 Linearly Coupled Spins

■ controls



■ drift: Ising (ZZ) and Heisenberg (XX) interactions



I. Quantum
Compilation

II. Quantum Control

Optimising on $PSU(N)$

Decoherence Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

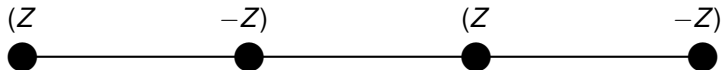
Conclusions &
Outlook



Examples of Quantum Control

3. Model Systems: 4 Linearly Coupled Spins

■ controls



■ drift: Ising (ZZ) and Heisenberg (XX,XXX) interactions



I. Quantum
Compilation

II. Quantum Control

Optimising on $PSU(N)$

Decoherence Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook



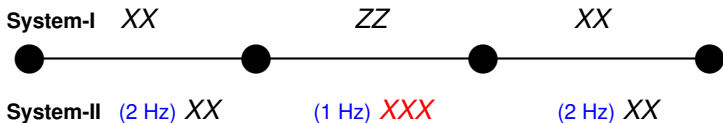
Examples of Quantum Control

3. Model Systems: 4 Linearly Coupled Spins

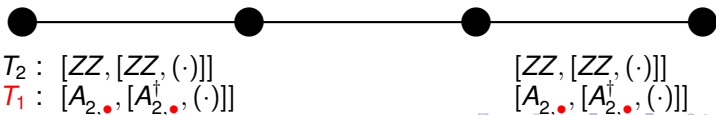
■ controls



■ drift: Ising (ZZ) and Heisenberg (XX,XXX) interactions



■ relaxation ($T_2^{-1} : T_1^{-1} = 4.0 \text{ s}^{-1} : 0.024 \text{ s}^{-1} \simeq 170 : 1$)





Examples of Quantum Control

3. Model Systems: Algebraic Analysis

I. Quantum
Compilation

II. Quantum Control

Optimising on $PSU(N)$

Decoherence Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook

■ System-I: staying **within** slowly-relaxing subspace

- drift Hamiltonian D_1 with **Ising-ZZ**
- controls $C_{1,2}$

$$D_1 := J_{xx} (xx\mathbb{1}\mathbb{1} + \mathbb{1}\mathbb{1}xx + yy\mathbb{1}\mathbb{1} + \mathbb{1}\mathbb{1}yy) + J_{zz} \mathbb{1}zz\mathbb{1}$$

$$C_1 := z\mathbb{1}\mathbb{1}\mathbb{1} - \mathbb{1}z\mathbb{1}\mathbb{1}$$

$$C_2 := \mathbb{1}\mathbb{1}z\mathbb{1} - \mathbb{1}\mathbb{1}\mathbb{1}z .$$

$$\Rightarrow \langle D_1, C_1, C_2 \rangle_{\text{Lie}} \Big|_{\mathcal{B} \otimes \mathcal{B}} \stackrel{\text{iso}}{=} \mathfrak{su}(4)$$

- Liouville subspace $\mathcal{B} \otimes \mathcal{B}$
spans states protected against T_2 -relaxation



Examples of Quantum Control

3. Model Systems: Algebraic Analysis

I. Quantum
Compilation

II. Quantum Control
Optimising on $PSU(N)$
Decoherence Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook

■ System-I: staying **within** slowly-relaxing subspace

- drift Hamiltonian D_1 with **Ising-ZZ**
- controls $C_{1,2}$

$$D_1 := J_{xx} (xx\mathbb{1}\mathbb{1} + \mathbb{1}\mathbb{1}xx + yy\mathbb{1}\mathbb{1} + \mathbb{1}\mathbb{1}yy) + J_{zz} \mathbb{1}zz\mathbb{1}$$

$$C_1 := z\mathbb{1}\mathbb{1}\mathbb{1} - \mathbb{1}z\mathbb{1}\mathbb{1}$$

$$C_2 := \mathbb{1}\mathbb{1}z\mathbb{1} - \mathbb{1}\mathbb{1}\mathbb{1}z .$$

$$\Rightarrow \langle D_1, C_1, C_2 \rangle_{\text{Lie}} \Big|_{\mathcal{B} \otimes \mathcal{B}} \stackrel{\text{iso}}{=} \mathfrak{su}(4)$$

- Liouville subspace $\mathcal{B} \otimes \mathcal{B}$
spans states protected against T_2 -relaxation



Examples of Quantum Control

3. Model Systems: Algebraic Analysis

I. Quantum
Compilation

II. Quantum Control
Optimising on $PSU(N)$
Decoherence Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook

- **System-II**: driving **outside** slowly-relaxing subspace
 - drift: extended to **isotropic Heisenberg-XXX**

$$D_1 + D_2 := J_{xx} (xx\mathbf{11} + \mathbf{11}xx + yy\mathbf{11} + \mathbf{11}yy) \\ + J_{xyz} (\mathbf{1}xx\mathbf{1} + \mathbf{1}yy\mathbf{1} + \mathbf{1}zz\mathbf{1})$$

- Lie-algebraic closure: in **66-dim. Lie algebra**

$$\dim\langle (D_1 + D_2), C_1, C_2 \rangle_{\text{Lie}} = 66 ,$$

- **$su(4)$** merely **subalgebra**



Examples of Quantum Control

3. Model Systems: Algebraic Analysis

I. Quantum
Compilation

II. Quantum Control
Optimising on $PSU(N)$
Decoherence Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook

- **System-II**: driving **outside** slowly-relaxing subspace
 - drift: extended to **isotropic Heisenberg-XXX**

$$D_1 + D_2 := J_{xx} (xx\mathbf{11} + \mathbf{11}xx + yy\mathbf{11} + \mathbf{11}yy) \\ + J_{xyz} (\mathbf{1}xx\mathbf{1} + \mathbf{1}yy\mathbf{1} + \mathbf{1}zz\mathbf{1})$$

- Lie-algebraic closure: in **66-dim. Lie algebra**

$$\dim\langle (D_1 + D_2), C_1, C_2 \rangle_{\text{Lie}} = 66 ,$$

- **su(4)** merely **subalgebra**



Examples of Quantum Control

3. Model Systems: Algebraic Analysis

I. Quantum
Compilation

II. Quantum Control
Optimising on $PSU(N)$
Decoherence Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook

- **System-II**: driving **outside** slowly-relaxing subspace
 - drift: extended to **isotropic Heisenberg-XXX**

$$D_1 + D_2 := J_{xx} (xx\mathbf{11} + \mathbf{11}xx + yy\mathbf{11} + \mathbf{11}yy) \\ + J_{xyz} (\mathbf{1}xx\mathbf{1} + \mathbf{1}yy\mathbf{1} + \mathbf{1}zz\mathbf{1})$$

- Lie-algebraic closure: in **66-dim. Lie algebra**

$$\dim\langle (D_1 + D_2), C_1, C_2 \rangle_{\text{Lie}} = 66 ,$$

- $\mathfrak{su}(4)$ merely **subalgebra**



Examples of Quantum Control

3. Model Systems: Algebraic Analysis

System-II:

- full controllability **within** slowly-relaxing subspace

- observation

$$e^{-i\pi C_1}(D_1 + D_2)e^{i\pi C_1} = D_1 - D_2$$

- Trotter limit

$$\lim_{n \rightarrow \infty} (e^{-i(D_1 + D_2)/(2n)} e^{-i(D_1 - D_2)/(2n)})^n = e^{-iD_1}$$

- reduction of dynamics

System-II $\xrightarrow{\text{infinite \# switchings}}$ System-I

I. Quantum
Compilation

II. Quantum Control

Optimising on $PSU(N)$

Decoherence Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook



Examples of Quantum Control

3. Model Systems: Algebraic Analysis

System-II:

- full controllability **within** slowly-relaxing subspace

- observation

$$e^{-i\pi C_1}(D_1 + D_2)e^{i\pi C_1} = D_1 - D_2$$

- Trotter limit

$$\lim_{n \rightarrow \infty} (e^{-i(D_1 + D_2)/(2n)} e^{-i(D_1 - D_2)/(2n)})^n = e^{-iD_1}$$

- reduction of dynamics

System-II $\xrightarrow{\text{infinite \# switchings}}$ System-I

I. Quantum
Compilation

II. Quantum Control

Optimising on $PSU(N)$

Decoherence Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook



Examples of Quantum Control

3. Model Systems: Algebraic Analysis

System-II:

- full controllability **within** slowly-relaxing subspace

- observation

$$e^{-i\pi C_1}(D_1 + D_2)e^{i\pi C_1} = D_1 - D_2$$

- Trotter limit

$$\lim_{n \rightarrow \infty} (e^{-i(D_1 + D_2)/(2n)} e^{-i(D_1 - D_2)/(2n)})^n = e^{-iD_1}$$

- reduction of dynamics

System-II $\xrightarrow{\text{infinite \# switchings}}$ **System-I**

I. Quantum
Compilation

II. Quantum Control

Optimising on $PSU(N)$

Decoherence Control

SP4: Dissemination

SP4: Perspectives

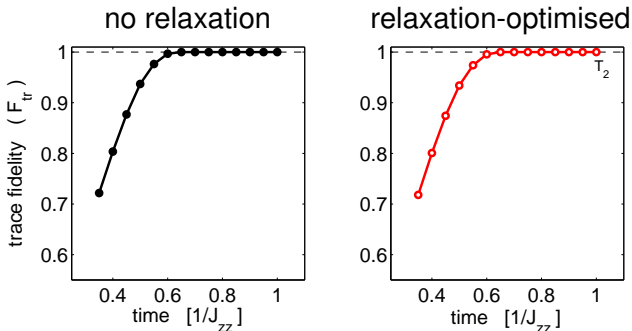
III. Local Control

Conclusions &
Outlook

Examples of Quantum Control

3. Model Systems: 4 Linearly Coupled Spins

- **System-I:** staying **within** slowly-relaxing subspace



- T_2 -relaxation has **no effect** on quality

I. Quantum
Compilation

II. Quantum Control

Optimising on $PSU(N)$

Decoherence Control

SP4: Dissemination

SP4: Perspectives

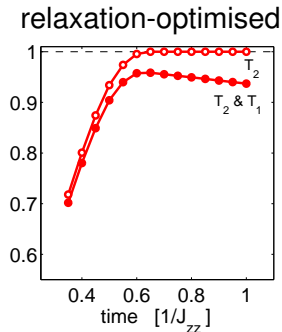
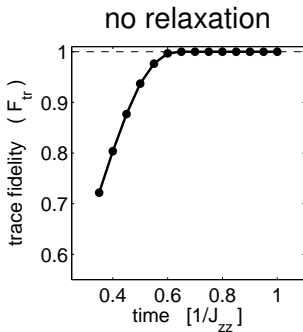
III. Local Control

Conclusions &
Outlook

Examples of Quantum Control

3. Model Systems: 4 Linearly Coupled Spins

■ System-I: staying **within** slowly-relaxing subspace



- T_2 -relaxation has **no effect** on quality
- additional T_1 -relaxation **drops** quality

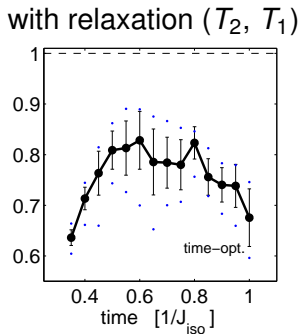
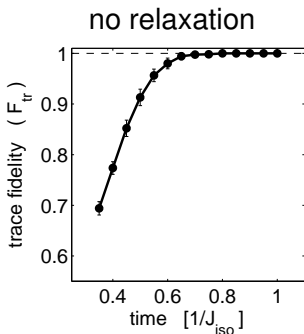




Examples of Quantum Control

3. Model System: 2 Qubits by 4 Spins

■ System-II: driving **outside** slowly-relaxing subspace

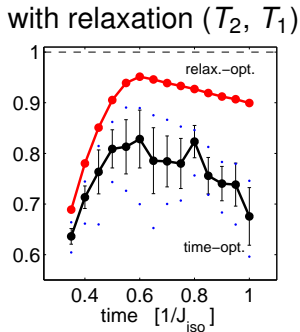
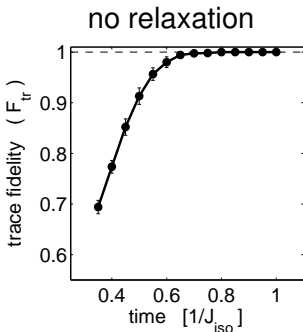


- mean of 15 time-optimised pulse sequences
- dissipation affects sequences differently

Examples of Quantum Control

3. Model System: 2 Qubits by 4 Spins

■ System-II: driving **outside** slowly-relaxing subspace



- mean of 15 time-optimised pulse sequences
- dissipation affects sequences differently
- relaxation-optimised: **systematic substantial gain**



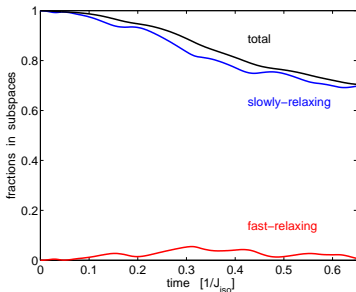


Examples of Quantum Control

3. Realising Quantum Gates with Minimal Relaxation

CNOT under **System-II**: Projection into Subspaces

■ time-optimal



I. Quantum
Compilation

II. Quantum Control

Optimising on $PSU(N)$

Decoherence Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook

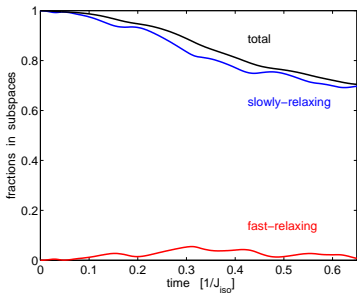


Examples of Quantum Control

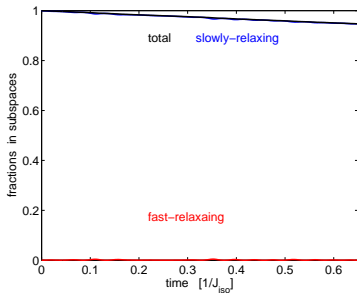
3. Realising Quantum Gates with Minimal Relaxation

CNOT under **System-II**: Projection into Subspaces

■ time-optimal



■ opt. against decoherence



I. Quantum
Compilation

II. Quantum Control

Optimising on $PSU(N)$

Decoherence Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

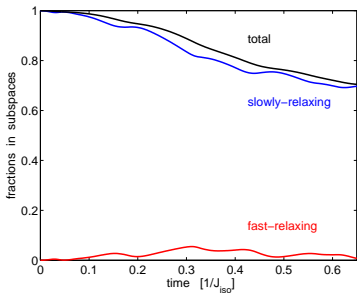
Conclusions &
Outlook

Examples of Quantum Control

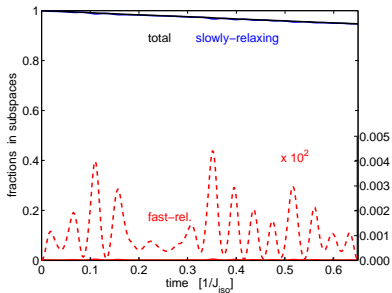
3. Realising Quantum Gates with Minimal Relaxation

CNOT under **System-II**: Projection into Subspaces

■ time-optimal



■ opt. against decoherence



I. Quantum Compilation

II. Quantum Control

Optimising on $PSU(N)$

Decoherence Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions & Outlook

Examples of Quantum Control

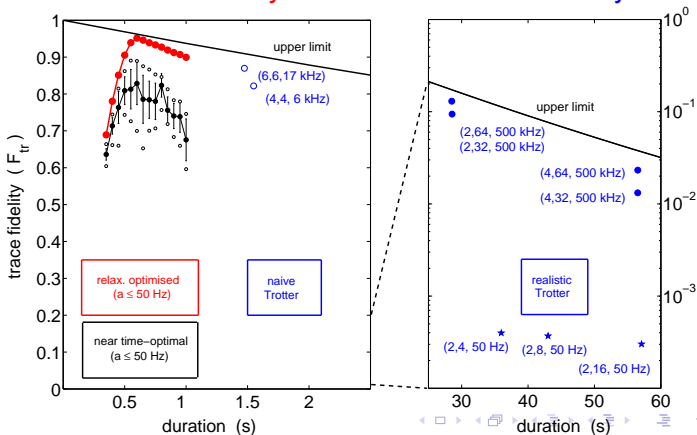
3. Realising Quantum Gates with Minimal Relaxation

quant-ph/0609037

■ CNOT under **System-II**: comparison of methods

by decoherence control:
> 95% fidelity

conventional:
< 15% fidelity



I. Quantum Compilation

II. Quantum Control

Optimising on $PSU(N)$

Decoherence Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions & Outlook



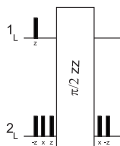
Decoherence Control

Alternative by Recursive TROTTER

- I. Quantum Compilation
- II. Quantum Control
 - Optimising on $PSU(N)$
 - Decoherence Control
- SP4: Dissemination
- SP4: Perspectives
- III. Local Control
- Conclusions & Outlook

Decoherence-Protected CNOT-Gate via

- logical qubits

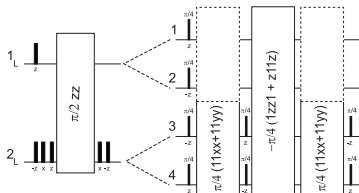


Decoherence Control

Alternative by Recursive TROTTER

Decoherence-Protected CNOT-Gate via

■ physical qubits

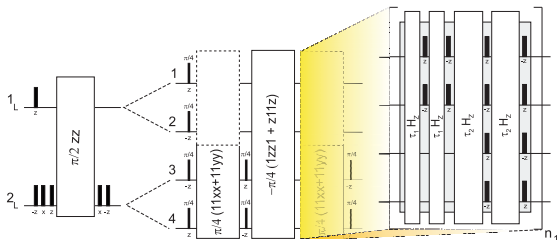


Decoherence Control

Alternative by Recursive TROTTER

Decoherence-Protected CNOT-Gate via

■ realisation by **System-I**



I. Quantum
Compilation

II. Quantum Control

Optimising on $PSU(N)$

Decoherence Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook



Decoherence Control

Alternative by Recursive TROTTER

Decoherence-Protected CNOT-Gate via

■ realisation by **System-II**

I. Quantum
Compilation

II. Quantum Control

Optimising on $PSU(N)$

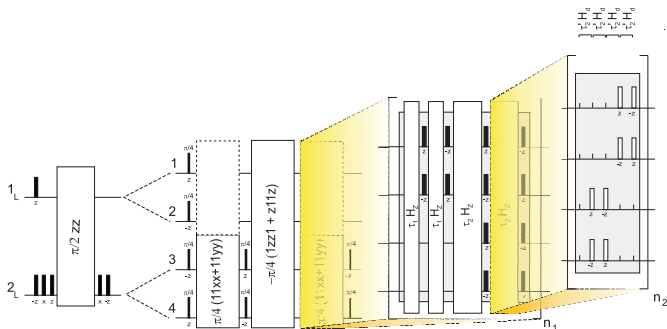
Decoherence Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook





Controlling Decoherence:

Take-Home Message

Which Tool in Which Setting?

1. *“anything goes”*: Paul FEYERABEND
only in **ideal** case: decoherence-**free**,
fully **controllable and closed** under drift
2. *Timeoptimal Control*:
whenever **slowly**-relaxing subsystem **controllable**
and closed under drift
3. *Relaxation-Optimised Control*:
whenever **slowly**-relaxing subsystem **open**, where
subsystem
 - (i) **controllable** or
 - (ii) **to be extended** for controllability



Controlling Decoherence:

Take-Home Message

Which Tool in Which Setting?

1. *“anything goes”*: Paul FEYERABEND
only in **ideal** case: decoherence-**free**,
fully **controllable and closed** under drift
2. *Timeoptimal Control*:
whenever **slowly**-relaxing subsystem **controllable and closed** under drift
3. *Relaxation-Optimised Control*:
whenever **slowly**-relaxing subsystem **open**, where
subsystem
(i) **controllable** or
(ii) **to be extended** for controllability



Controlling Decoherence:

Take-Home Message

Which Tool in Which Setting?

1. *“anything goes”*: Paul FEYERABEND
only in **ideal** case: decoherence-**free**,
fully **controllable and closed** under drift
2. *Timeoptimal Control*:
whenever **slowly**-relaxing subsystem **controllable
and closed** under drift
3. *Relaxation-Optimised Control*:
whenever **slowly**-relaxing subsystem **open**, where
subsystem
 - (i) **controllable** or
 - (ii) **to be extended** for controllability



Dissemination of GRAPE for SP4

as User-Friendly MATLAB Package v1.0

Contents:

- README
- general routines:
 - setup_your_system.m
 - octane.m
 - par_fit.m
 - maxStepSize2b.m
- worked NMR examples:
 - (1) CNOT: setup_NMR_2spins.m
 - (2) TOFFOLI, 3-qubit QFT: setup_NMR_3spins.m
- general 3-level system:
 - (1) one on-resonance field with amplitude and xy-phase control
setup_3level_optical_system.m
 - (2) one detuned field with amplitude control and fixed phase (x)
setup_3level_optical_system_detuned.m
- references: *J.Magn.Res.* **172**, 296 (2005) & *PRA* **72** 042331 (2005)
 - ref1.pdf
 - ref2.pdf



Dissemination of GRAPE for SP4

as User-Friendly MATLAB Package v1.0

I. Quantum
Compilation

II. Quantum Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook

Contents:

- README
- general routines:
 - setup_your_system.m
 - octane.m
 - par_fit.m
 - maxStepSize2b.m
- worked NMR examples:
 - (1) CNOT: setup_NMR_2spins.m
 - (2) TOFFOLI, 3-qubit QFT: setup_NMR_3spins.m
- general 3-level system:
 - (1) one on-resonance field with amplitude and xy-phase control
setup_3level_optical_system.m
 - (2) one detuned field with amplitude control and fixed phase (x)
setup_3level_optical_system_detuned.m
- references: *J.Magn.Res.* **172**, 296 (2005) & *PRA* **72** 042331 (2005)
 - ref1.pdf
 - ref2.pdf



Dissemination of GRAPE for SP4

as User-Friendly MATLAB Package v1.0

I. Quantum
Compilation

II. Quantum Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook

Contents:

- README
- general routines:
 - `setup_your_system.m`
 - `octane.m`
 - `par_fit.m`
 - `maxStepSize2b.m`
- worked NMR examples:
 - (1) CNOT: `setup_NMR_2spins.m`
 - (2) TOFFOLI, 3-qubit QFT: `setup_NMR_3spins.m`
- general 3-level system:
 - (1) one on-resonance field with amplitude and xy-phase control
`setup_3level_optical_system.m`
 - (2) one detuned field with amplitude control and fixed phase (x)
`setup_3level_optical_system_detuned.m`
- references: *J.Magn.Res.* **172**, 296 (2005) & *PRA* **72** 042331 (2005)
 - `ref1.pdf`
 - `ref2.pdf`



Dissemination of GRAPE for SP4

as User-Friendly MATLAB Package v1.0

Contents:

- README
- general routines:
 - `setup_your_system.m`
 - `octane.m`
 - `par_fit.m`
 - `maxStepSize2b.m`
- worked NMR examples:
 - (1) CNOT: `setup_NMR_2spins.m`
 - (2) TOFFOLI, 3-qubit QFT: `setup_NMR_3spins.m`
- general 3-level system:
 - (1) one on-resonance field with amplitude and xy-phase control
`setup_3level_optical_system.m`
 - (2) one detuned field with amplitude control and fixed phase (x)
`setup_3level_optical_system_detuned.m`
- references: *J.Magn.Res.* **172**, 296 (2005) & *PRA* **72** 042331 (2005)
 - `ref1.pdf`
 - `ref2.pdf`



Dissemination of GRAPE for SP4

as User-Friendly MATLAB Package v1.0

Contents:

- README
- general routines:
 - `setup_your_system.m`
 - `octane.m`
 - `par_fit.m`
 - `maxStepSize2b.m`
- worked NMR examples:
 - (1) CNOT: `setup_NMR_2spins.m`
 - (2) TOFFOLI, 3-qubit QFT: `setup_NMR_3spins.m`
- general 3-level system:
 - (1) one on-resonance field with amplitude and xy-phase control
`setup_3level_optical_system.m`
 - (2) one detuned field with amplitude control and fixed phase (x)
`setup_3level_optical_system_detuned.m`
- references: *J.Magn.Res.* **172**, 296 (2005) & *PRA* **72** 042331 (2005)
 - `ref1.pdf`
 - `ref2.pdf`



Dissemination of GRAPE for SP4

as User-Friendly MATLAB Package v1.0

How to run the package in MATLAB.

1. Setup up system:

- choose example

`setup_NMR_3spins, setup_3level_optical_system...`

- or create own setup with H_{drift} and H_{control}

`setup_your_system`

- specify target unitary gate

2. Run `octane.m` for fixed final time T :

- use output of the setup as input

`type help octane` for instructions

3. Find minimum time by tracking:

- rerun with decreasing final times T

till fidelity falls short of threshold (>0.99999)

I. Quantum
Compilation

II. Quantum Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook



Dissemination of GRAPE for SP4

as User-Friendly MATLAB Package v1.0

How to run the package in MATLAB.

1. Setup up system:

- choose example

```
setup_NMR_3spins, setup_3level_optical_system...
```

- or create own setup with H_{drift} and H_{control}

```
setup_your_system
```

- specify target unitary gate

2. Run `octane.m` for fixed final time T :

- use output of the setup as input
type `help octane` for instructions

3. Find minimum time by tracking:

- rerun with decreasing final times T
till fidelity falls short of threshold (>0.99999)

I. Quantum
Compilation

II. Quantum Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook



Dissemination of GRAPE for SP4

as User-Friendly MATLAB Package v1.0

How to run the package in MATLAB.

1. Setup up system:

- choose example

```
setup_NMR_3spins, setup_3level_optical_system ...
```

- or create own setup with H_{drift} and H_{control}

```
setup_your_system
```

- specify target unitary gate

2. Run `octane.m` for fixed final time T :

- use output of the setup as input
type `help octane` for instructions

3. Find minimum time by tracking:

- rerun with decreasing final times T
till fidelity falls short of threshold (>0.99999)

I. Quantum
Compilation

II. Quantum Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook



Dissemination of GRAPE for SP4

as User-Friendly MATLAB Package v1.0

Checks for MATLAB (run in faster non-JAVA version).

■ worked example A: CNOT in 2 qubits

- run `setup_NMR_2spins`
- run `octane(32, 7e3, 1, ones(1, 4), .5, 'myPulse.mat')`
- test fidelity 0.99963 in 1489s (Pentium III 933.377MHz)

■ worked example B: TOFFOLI in 3 qubits

- run `setup_NMR_3spins`
- run `octane(64, 1e4, 1, ones(1, 6), 2, 'myPulse.mat')`
- test fidelity 0.99988
- in 5419s on an Intel(R) Pentium(R) 4 CPU 2.66GHz

■ example C: π X GATE in lower 2 levels of 3-level system

- run `setup_3level_optical_system`
- run `octane(64, 1e4, 1, ones(1, 2), 2, 'myPulse.mat')`
- test fidelity 0.99999
- in 151s on an Intel(R) Pentium(R) 4 CPU 2.66GHz

I. Quantum
Compilation

II. Quantum Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook



Dissemination of GRAPE for SP4

as User-Friendly MATLAB Package v1.0

Checks for MATLAB (run in faster non-JAVA version).

■ worked example A: CNOT in 2 qubits

- run `setup_NMR_2spins`
- run `octane(32, 7e3, 1, ones(1, 4), .5, 'myPulse.mat')`
- test fidelity 0.99963 in 1489s (Pentium III 933.377MHz)

■ worked example B: TOFFOLI in 3 qubits

- run `setup_NMR_3spins`
- run `octane(64, 1e4, 1, ones(1, 6), 2, 'myPulse.mat')`
- test fidelity 0.99988
- in 5419s on an Intel(R) Pentium(R) 4 CPU 2.66GHz

■ example C: π X GATE in lower 2 levels of 3-level system

- run `setup_3level_optical_system`
- run `octane(64, 1e4, 1, ones(1, 2), 2, 'myPulse.mat')`
- test fidelity 0.99999
- in 151s on an Intel(R) Pentium(R) 4 CPU 2.66GHz

I. Quantum
Compilation

II. Quantum Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook



Dissemination of GRAPE for SP4

as User-Friendly MATLAB Package v1.0

Checks for MATLAB (run in faster non-JAVA version).

■ worked example A: CNOT in 2 qubits

- run `setup_NMR_2spins`
- run `octane(32, 7e3, 1, ones(1, 4), .5, 'myPulse.mat')`
- test fidelity 0.99963 in 1489s (Pentium III 933.377MHz)

■ worked example B: TOFFOLI in 3 qubits

- run `setup_NMR_3spins`
- run `octane(64, 1e4, 1, ones(1, 6), 2, 'myPulse.mat')`
- test fidelity 0.99988
- in 5419s on an Intel(R) Pentium(R) 4 CPU 2.66GHz

■ example C: π X GATE in lower 2 levels of 3-level system

- run `setup_3level_optical_system`
- run `octane(64, 1e4, 1, ones(1, 2), 2, 'myPulse.mat')`
- test fidelity 0.99999
- in 151s on an Intel(R) Pentium(R) 4 CPU 2.66GHz

I. Quantum
Compilation

II. Quantum Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook



SP4: Joint Perspective for Open Systems

I. Quantum
Compilation

II. Quantum Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook

■ Starting Point: [quant-ph/0609037](https://arxiv.org/abs/quant-ph/0609037)

- optimal control of Markovian dissipative systems

$$\dot{\rho} = -i[H, \rho] + \Gamma\rho = -i[H, \rho] + \frac{1}{2} \sum_j [L_j, \rho L_j^\dagger] + [L_j \rho, L_j^\dagger]$$

■ Experimental Systems: Quantum Process Tomography

- quantum maps $\rho_{\text{out}} = \mathcal{E}(\rho) = \sum_k E_k^\dagger \rho_{\text{in}} E_k$

■ Conversion into Approximate Lindbladian:

- see: Boulant, Havel, Pravia, Cory, *PRA* **67**, 042322 (2003)

$$\dot{\rho} = -i[H, \rho] + \frac{1}{2} \sum_j [L_j, \rho L_j^\dagger] + [L_j \rho, L_j^\dagger]$$

- application: *New J. Phys.* **8**, 33 (2006)



SP4: Joint Perspective for Open Systems

I. Quantum
Compilation

II. Quantum Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook

■ Starting Point: [quant-ph/0609037](https://arxiv.org/abs/quant-ph/0609037)

- optimal control of Markovian dissipative systems

$$\dot{\rho} = -i[H, \rho] + \Gamma\rho = -i[H, \rho] + \frac{1}{2} \sum_j [L_j, \rho L_j^\dagger] + [L_j \rho, L_j^\dagger]$$

■ Experimental Systems: Quantum Process Tomography

- quantum maps $\rho_{\text{out}} = \mathcal{E}(\rho) = \sum_k E_k^\dagger \rho_{\text{in}} E_k$

■ Conversion into Approximate Lindbladian:

- see: Boulant, Havel, Pravia, Cory, *PRA* **67**, 042322 (2003)

$$\dot{\rho} = -i[H, \rho] + \frac{1}{2} \sum_j [L_j, \rho L_j^\dagger] + [L_j \rho, L_j^\dagger]$$

- application: *New J. Phys.* **8**, 33 (2006)



SP4: Joint Perspective for Open Systems

I. Quantum
Compilation

II. Quantum Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook

■ Starting Point: quant-ph/0609037

- optimal control of Markovian dissipative systems

$$\dot{\rho} = -i[H, \rho] + \Gamma\rho = -i[H, \rho] + \frac{1}{2} \sum_j [L_j, \rho L_j^\dagger] + [L_j \rho, L_j^\dagger]$$

■ Experimental Systems: Quantum Process Tomography

- quantum maps $\rho_{\text{out}} = \mathcal{E}(\rho) = \sum_k E_k^\dagger \rho_{\text{in}} E_k$

■ Conversion into Approximate Lindbladian:

- see: Boulant, Havel, Pravia, Cory, *PRA* **67**, 042322 (2003)

$$\dot{\rho} = -i[H, \rho] + \frac{1}{2} \sum_j [L_j, \rho L_j^\dagger] + [L_j \rho, L_j^\dagger]$$

- application: *New J. Phys.* **8**, 33 (2006)

New Journal of Physics

The open-access journal for physics

**Quantum process tomography and Linblad
estimation of a solid-state qubit**

M Howard¹, J Twamley^{2,4}, C Wittmann³, T Gaebel³, F Jelezko³
and J Wrachtrup³



The Local C -Numerical Range

Local Quantum Control

with G. Dirr & U. Helmke

Definition (math-ph/0701037, math-ph/0702005)

The *local C -numerical range* is the set

$$W_{\text{loc}}(C, A) := \{\text{tr}(C^\dagger UAU^\dagger) \mid U \in SU(2)^{\otimes n}\} \subseteq W_C(A),$$

where the unitary orbit is restricted to *local operations*

$$U =: K \in SU(2) \otimes SU(2) \otimes \cdots \otimes SU(2)$$

I. Quantum
Compilation

II. Quantum Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Local Numerical Ranges

Local Gradient Flows

Pure-State Entanglement

Local Timereversal

Conclusions &
Outlook



The Local C -Numerical Range

Local Quantum Control

with G. Dirr & U. Helmke

I. Quantum
Compilation

II. Quantum Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Local Numerical Ranges

Local Gradient Flows

Pure-State Entanglement

Local Timereversal

Conclusions &
Outlook

Definition (math-ph/0701037, math-ph/0702005)

The *local C -numerical range* is the set

$$W_{\text{loc}}(C, A) := \{\text{tr}(C^\dagger UAU^\dagger) \mid U \in SU(2)^{\otimes n}\} \subseteq W_C(A),$$

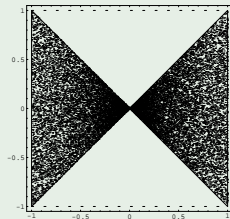
where the unitary orbit is restricted to *local operations*

$$U =: K \in SU(2) \otimes SU(2) \otimes \cdots \otimes SU(2)$$

Example (non convex)

$$A := \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \otimes \begin{pmatrix} 1+i & 0 \\ 0 & 1-i \end{pmatrix}$$

$$C := \text{diag}(1, 0, 0, 0)$$





The Local C -Numerical Range

Local Quantum Control

with G. Dirr & U. Helmke

- I. Quantum Compilation
- II. Quantum Control
 - SP4: Dissemination
 - SP4: Perspectives
- III. Local Control
 - Local Numerical Ranges
 - Local Gradient Flows
 - Pure-State Entanglement
 - Local Timereversal
- Conclusions & Outlook

Definition (math-ph/0701037, math-ph/0702005)

The *local C -numerical range* is the set

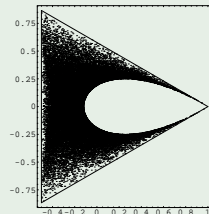
$$W_{\text{loc}}(C, A) := \{\text{tr}(C^\dagger UAU^\dagger) \mid U \in SU(2)^{\otimes n}\} \subseteq W_C(A),$$

where the unitary orbit is restricted to *local operations*
 $U =: K \in SU(2) \otimes SU(2) \otimes \cdots \otimes SU(2)$

Example (neither star-shaped nor simply connected)

$$A := \begin{pmatrix} 1 & 0 \\ 0 & e^{2i\pi/3} \end{pmatrix}^{\otimes 3}$$

$$C := \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}^{\otimes 3}$$





I. Quantum
Compilation

II. Quantum Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Local Numerical Ranges

Local Gradient Flows

Pure-State Entanglement

Local Timereversal

Conclusions &
Outlook

- Gradient flow on *local* unitaries

$$\begin{aligned}\dot{K} &= \text{grad } f(K) = P_{\mathfrak{k}}([(KHK^{-1}), H]) K \\ &= -P_{\mathfrak{k}}(\text{ad}_H \circ \text{Ad}_K(H)) K ,\end{aligned}$$

$P_{\mathfrak{k}}$: projection onto subalgebra \mathfrak{k} of generators of local unitaries $\mathbf{K} = \mathbf{SU}(2)^{\otimes n}$.



- I. Quantum Compilation
- II. Quantum Control
- SP4: Dissemination
- SP4: Perspectives
- III. Local Control
 - Local Numerical Ranges
 - Local Gradient Flows
 - Pure-State Entanglement
 - Local Timereversal
- Conclusions & Outlook

- Maximising real part in $W_{\text{loc}}(C, A)$
 minimises distance from C to *local unitary orbit* of A

$$\max_{K \in SU(2)^{\otimes n}} \text{Re tr}\{C^\dagger KAK^{-1}\} \Leftrightarrow \min_{K \in SU(2)^{\otimes n}} \|KAK^{-1} - C\|_2$$

- Application to Quantum Information Theory: let A be a given rank-1 state of the form $A = |\psi\rangle\langle\psi|$ and $C = \text{diag}(1, 0)^{\otimes n}$ [thus $W_{\text{loc}}(C, A) \rightarrow W_{\text{loc}}(A)$]

Corollary (Interpretation)

The minimal Euclidean distance is a measure of (pure-state) entanglement; i.e. it quantifies how far A is from the local equivalence class of the tensor-product state C .



- I. Quantum Compilation
- II. Quantum Control
- SP4: Dissemination
- SP4: Perspectives
- III. Local Control
 - Local Numerical Ranges
 - Local Gradient Flows
 - Pure-State Entanglement
 - Local Timereversal
- Conclusions & Outlook

- Maximising real part in $W_{\text{loc}}(C, A)$
 minimises distance from C to *local unitary orbit* of A

$$\max_{K \in SU(2)^{\otimes n}} \text{Re tr}\{C^\dagger KAK^{-1}\} \Leftrightarrow \min_{K \in SU(2)^{\otimes n}} \|KAK^{-1} - C\|_2$$

- Application to Quantum Information Theory: let A be a given rank-1 state of the form $A = |\psi\rangle\langle\psi|$ and $C = \text{diag}(1, 0)^{\otimes n}$ [thus $W_{\text{loc}}(C, A) \rightarrow W_{\text{loc}}(A)$]

Corollary (Interpretation)

*The minimal Euclidean distance is a **measure of (pure-state) entanglement**; i.e. it quantifies how far A is from the **local equivalence class** of the tensor-product state C .*



I. Quantum
Compilation

II. Quantum Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Local Numerical Ranges

Local Gradient Flows

Pure-State Entanglement

Local Timereversal

Conclusions &
Outlook

- Maximising real part in $W_{\text{loc}}(C, A)$
minimises distance from C to *local unitary orbit* of A

$$\max_{K \in SU(2)^{\otimes n}} \text{Re tr}\{C^\dagger KAK^{-1}\} \Leftrightarrow \min_{K \in SU(2)^{\otimes n}} \|KAK^{-1} - C\|_2$$

- Application to Quantum Information Theory: let
 A be a given rank-1 state of the form $A = |\psi\rangle\langle\psi|$ and
 $C = \text{diag}(1, 0)^{\otimes n}$ [thus $W_{\text{loc}}(C, A) \rightarrow W_{\text{loc}}(A)$]

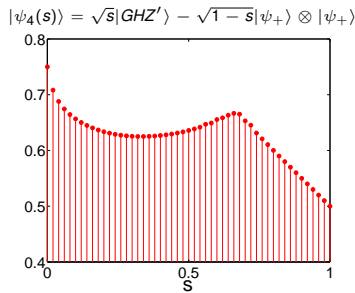
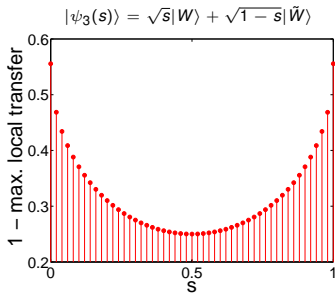
Corollary (Interpretation)

*The minimal Euclidean distance is a **measure of (pure-state) entanglement**; i.e. it quantifies how far A is from the **local equivalence class** of the tensor-product state C .*



- I. Quantum Compilation
- II. Quantum Control
 - SP4: Dissemination
 - SP4: Perspectives
- III. Local Control
 - Local Numerical Ranges
 - Local Gradient Flows
 - Pure-State Entanglement
 - Local Timereversal
- Conclusions & Outlook

■ Examples: pure-state entanglement parameterised by s





- I. Quantum Compilation
- II. Quantum Control
 - SP4: Dissemination
 - SP4: Perspectives
- III. Local Control
 - Local Numerical Ranges
 - Local Gradient Flows
 - Pure-State Entanglement
 - Local Timereversal

Conclusions & Outlook

- CPU times: local gradient flows
very fast as compared to global techniques
- Example 1: distance to 3-qubit W state
- Example 2: distance to 4-qubit GHZ-type state

qubits	polynomial optim. cpu-time [sec] ¹	by gradient flow cpu-time [sec] ²	speed-up
3	10.92	0.30	36.4
4	103.97	0.71	147.0

¹ Eisert *et al.* (processor with 2.2 GHz, 1 GB RAM)

² average of 50 runs, Athlon XP1800+ (1.1 GHz, 512 MB RAM)



■ Task: time reversal by *local* operations

Decide whether sign-reversed Hamiltonian $-H$ is on the *local unitary orbit* of the original Hamiltonian H !
 $? \exists K \in SU(2)^{\otimes n} : K e^{-itH} K = e^{+itH}$

Corollary (Local time reversal)

For $H = H^\dagger$ with $\|H\|_2 = 1$ the following are equivalent:

- *the Hamiltonian H is locally sign-reversible;*
- *its local C-numerical range comprises -1 ;*
 $-1 \in W_{\text{loc}}(H, H)$
- $\exists K \in SU(2)^{\otimes n} :$
 $\|KHK^{-1} + H\|_2^2 = 0 \Leftrightarrow \text{Ad}_K(H) = -H$



- Task: time reversal by *local* operations

Decide whether sign-reversed Hamiltonian $-H$ is on the *local unitary orbit* of the original Hamiltonian H !
 $? \exists K \in SU(2)^{\otimes n} : K e^{-itH} K = e^{+itH}$

Corollary (Local time reversal)

For $H = H^\dagger$ with $\|H\|_2 = 1$ the following are equivalent:

- 1 the Hamiltonian H is locally sign-reversible;
- 2 its *local C-numerical range* comprises -1 ;
 $-1 \in W_{\text{loc}}(H, H)$
- 3 $\exists K \in SU(2)^{\otimes n} :$
 $\|KHK^{-1} + H\|_2^2 = 0 \Leftrightarrow \text{Ad}_K(H) = -H$



- Task: time reversal by *local* operations

Decide whether sign-reversed Hamiltonian $-H$ is on the *local unitary orbit* of the original Hamiltonian H !
 $? \exists K \in SU(2)^{\otimes n} : K e^{-itH} K = e^{+itH}$

Corollary (Local time reversal)

For $H = H^\dagger$ with $\|H\|_2 = 1$ the following are equivalent:

- 1 the Hamiltonian H is locally sign-reversible;
- 2 its *local C-numerical range* comprises -1 ;
 $-1 \in W_{\text{loc}}(H, H)$
- 3 $\exists K \in SU(2)^{\otimes n} :$
 $\|KHK^{-1} + H\|_2^2 = 0 \Leftrightarrow \text{Ad}_K(H) = -H$



- Task: time reversal by *local* operations

Decide whether sign-reversed Hamiltonian $-H$ is on the *local unitary orbit* of the original Hamiltonian H !
? $\exists K \in SU(2)^{\otimes n} : K e^{-itH} K = e^{+itH}$

Corollary (Local time reversal)

For $H = H^\dagger$ with $\|H\|_2 = 1$ the following are equivalent:

- 1 the Hamiltonian H is locally sign-reversible;
- 2 its *local C-numerical range* comprises -1 ;
 $-1 \in W_{\text{loc}}(H, H)$
- 3 $\exists K \in SU(2)^{\otimes n} :$
 $\|KHK^{-1} + H\|_2^2 = 0 \Leftrightarrow \text{Ad}_K(H) = -H$



- Task: time reversal by *local* operations

Decide whether sign-reversed Hamiltonian $-H$ is on the *local unitary orbit* of the original Hamiltonian H !
? $\exists K \in SU(2)^{\otimes n} : K e^{-itH} K = e^{+itH}$

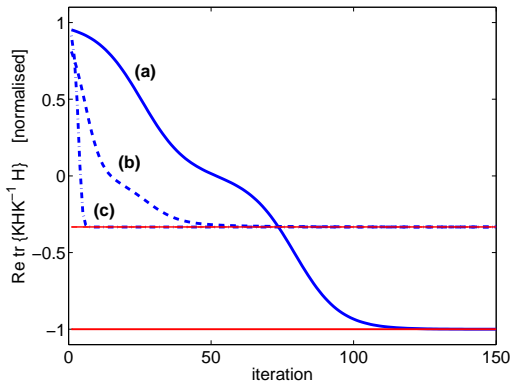
Corollary (Local time reversal)

For $H = H^\dagger$ with $\|H\|_2 = 1$ the following are equivalent:

- 1 the Hamiltonian H is locally sign-reversible;
- 2 its *local C-numerical range* comprises -1 ;
 $-1 \in W_{\text{loc}}(H, H)$
- 3 $\exists K \in SU(2)^{\otimes n} :$
 $\|KHK^{-1} + H\|_2^2 = 0 \Leftrightarrow \text{Ad}_K(H) = -H$

■ Examples

- (a) ISING ZZ-interaction on cyclic graph C_4 (bipartite)
- (b) ISING ZZ-interaction on cyclic graph C_3 (not bipartite)
- (c) HEISENBERG XXX interaction (isotropic coupling)





I. Quantum
Compilation

II. Quantum Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Local Numerical Ranges

Local Gradient Flows

Pure-State Entanglement

Local Timereversal

Conclusions &
Outlook

Corollary (Extension I: Local C -Numerical Range)

For $H = H^\dagger$ with $\|H\|_2 = 1$ the following are equivalent:

- 1 the Hamiltonian H is locally sign-reversible;
- 2 for its **local C -numerical range** $-1 \in W_{\text{loc}}(H, H)$;
- 3 its **local C -numerical range** is the interval
 $W_{\text{loc}}(H, H) = [-1; +1]$;



I. Quantum
Compilation

II. Quantum Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Local Numerical Ranges

Local Gradient Flows

Pure-State Entanglement

Local Timereversal

Conclusions &
Outlook

Corollary (Extension I: Local C -Numerical Range)

For $H = H^\dagger$ with $\|H\|_2 = 1$ the following are equivalent:

- 1 the Hamiltonian H is locally sign-reversible;
- 2 for its **local C -numerical range** $-1 \in W_{\text{loc}}(H, H)$;
- 3 its **local C -numerical range** is the interval

$$W_{\text{loc}}(H, H) = [-1; +1];$$



Corollary (Extension II: Lie algebras)

For $H = H^\dagger$ with $\|H\|_2 = 1$ the following are equivalent:

1 the Hamiltonian H is locally sign-reversible;

2 $\exists K \in SU(2)^{\otimes n} : \text{Ad}_K(H) = -H;$

3 H is locally unitarily similar to a \bar{H} with $\text{Ad}_{K_z}(\bar{H}) = -\bar{H};$

4 let $\mathfrak{g} = \mathfrak{g}_0 \oplus \bigoplus_{i \neq j} \mathbb{C} E_{ij}$ be the root-space decomposition of $\mathfrak{sl}(N, \mathbb{C});$ H is locally unitarily similar to a linear combination of root-space elements to non-zero roots $\bar{H} := \sum_{\lambda=1}^m c_\lambda E_{ij}^{(\lambda)}$ satisfying a system of linear equations $\sum_\ell p_{\lambda,\ell} \cdot \phi_\ell = \pi \pmod{2\pi}$



Corollary (Extension II: Lie algebras)

For $H = H^\dagger$ with $\|H\|_2 = 1$ the following are equivalent:

1 the Hamiltonian H is locally sign-reversible;

2 $\exists K \in SU(2)^{\otimes n} : \text{Ad}_K(H) = -H;$

3 H is locally unitarily similar to a \bar{H} with $\text{Ad}_{K_z}(\bar{H}) = -\bar{H};$

4 let $\mathfrak{g} = \mathfrak{g}_0 \oplus \bigoplus_{i \neq j} \mathbb{C} E_{ij}$ be the root-space

decomposition of $\mathfrak{sl}(N, \mathbb{C})$; H is locally unitarily similar to a linear combination of root-space

elements to non-zero roots $\bar{H} := \sum_{\lambda=1}^m c_\lambda E_{ij}^{(\lambda)}$

satisfying a system of linear equations

$$\sum_\ell p_{\lambda,\ell} \cdot \phi_\ell = \pi \pmod{2\pi}$$



- I. Quantum Compilation
- II. Quantum Control
- SP4: Dissemination
- SP4: Perspectives
- III. Local Control
 - Local Numerical Ranges
 - Local Gradient Flows
 - Pure-State Entanglement
 - Local Timereversal

Corollary (Extension II: Lie algebras)

For $H = H^\dagger$ with $\|H\|_2 = 1$ the following are equivalent:

- 1 the Hamiltonian H is locally sign-reversible;
- 2 $\exists K \in SU(2)^{\otimes n} : \text{Ad}_K(H) = -H$;
- 3 H is locally unitarily similar to a \bar{H} with $\text{Ad}_{K_z}(\bar{H}) = -\bar{H}$;
- 4 let $\mathfrak{g} = \mathfrak{g}_0 \oplus \bigoplus_{i \neq j} \mathbb{C} E_{ij}$ be the root-space decomposition of $\mathfrak{sl}(N, \mathbb{C})$; H is locally unitarily similar to a **linear combination of root-space elements to non-zero roots** $\bar{H} := \sum_{\lambda=1}^m c_\lambda E_{ij}^{(\lambda)}$ satisfying a system of linear equations $\sum_\ell p_{\lambda,\ell} \cdot \phi_\ell = \pi \pmod{2\pi}$



Conclusions

"Show me the big effects!"

1 Quantum Control: key in future technology

2 Timeoptimised Quantum Compilation

- dressed to physical hardware
- access to **time complexity**
- grossly fighting decoherence

3 Decoherence-Minimising Quantum Control

- progress towards controllability under dissipation

4 Local Time Reversal

- Hamiltonian simulation
- Hahn's spin echo by local controls

5 Local Optimisation

- pure-state entanglement
- new: local C -numerical range

I. Quantum
Compilation

II. Quantum Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook



Conclusions

"Show me the big effects!"

- 1 Quantum Control: key in future technology
- 2 Timeoptimised **Quantum Compilation**
 - dressed to physical hardware
 - access to **time complexity**
 - grossly fighting decoherence
- 3 **Decoherence-Minimising Quantum Control**
 - progress towards controllability under dissipation
- 4 Local Time Reversal
 - Hamiltonian simulation
 - Hahn's spin echo by local controls
- 5 Local Optimisation
 - pure-state entanglement
 - new: local C -numerical range

I. Quantum
Compilation

II. Quantum Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook



Conclusions

"Show me the big effects!"

- 1 Quantum Control: key in future technology
- 2 Timeoptimised **Quantum Compilation**
 - dressed to physical hardware
 - access to **time complexity**
 - grossly fighting decoherence
- 3 **Decoherence-Minimising Quantum Control**
 - progress towards controllability under dissipation
- 4 Local Time Reversal
 - Hamiltonian simulation
 - Hahn's spin echo by local controls
- 5 Local Optimisation
 - pure-state entanglement
 - new: local C -numerical range

I. Quantum
Compilation

II. Quantum Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook



Conclusions

"Show me the big effects!"

- 1 Quantum Control: key in future technology
- 2 Timeoptimised **Quantum Compilation**
 - dressed to physical hardware
 - access to **time complexity**
 - grossly fighting decoherence
- 3 **Decoherence-Minimising Quantum Control**
 - progress towards controllability under dissipation
- 4 Local Time Reversal
 - Hamiltonian simulation
 - Hahn's spin echo by local controls
- 5 Local Optimisation
 - pure-state entanglement
 - new: local **C-numerical range**

I. Quantum
Compilation

II. Quantum Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook



Conclusions

"Show me the big effects!"

- 1 Quantum Control: key in future technology
- 2 Timeoptimised **Quantum Compilation**
 - dressed to physical hardware
 - access to **time complexity**
 - grossly fighting decoherence
- 3 **Decoherence-Minimising Quantum Control**
 - progress towards controllability under dissipation
- 4 Local Time Reversal
 - Hamiltonian simulation
 - Hahn's spin echo by local controls
- 5 Local Optimisation
 - pure-state entanglement
 - new: local C -numerical range

I. Quantum
Compilation

II. Quantum Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

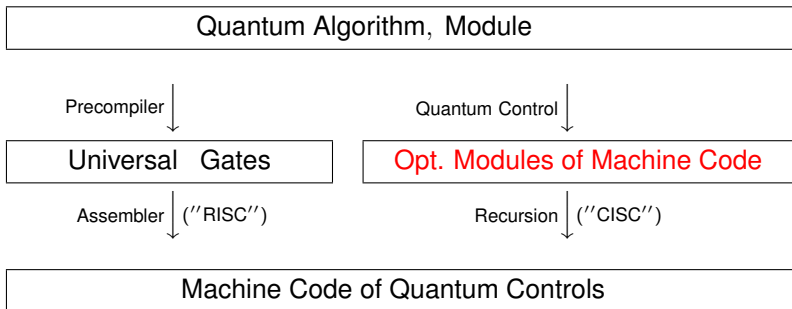
Conclusions &
Outlook



Outlook

Compilation by Recursion for Large Systems

- recursive use of **optimised medium-sized building blocks**



I. Quantum
Compilation

II. Quantum Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook



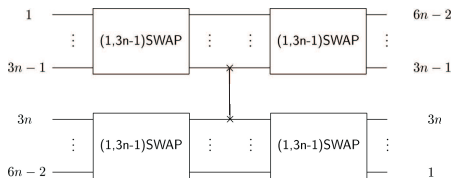
Recursion

Ex.: Recursive Indirect $(1, m)$ -SWAP on Linear Coupling Topology L_m

Goal: $(1, 6n)$ SWAP

Principal Ways:

1 via $(1, 3n)$



2 via $(1, 2n)$

I. Quantum
Compilation

II. Quantum Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook



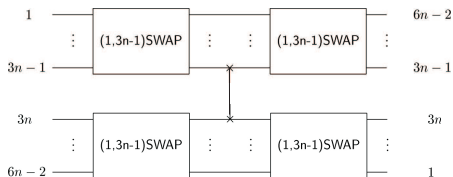
Recursion

Ex.: Recursive Indirect $(1, m)$ -SWAP on Linear Coupling Topology L_m

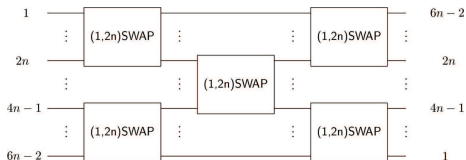
Goal: $(1, 6n)$ SWAP

Principal Ways:

1 via $(1, 3n)$



2 via $(1, 2n)$



I. Quantum
Compilation

II. Quantum Control

SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook



Recursion

Ex.: Recursive QFT

I. Quantum
Compilation

II. Quantum Control

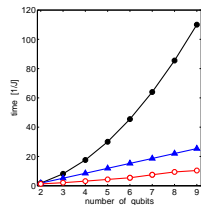
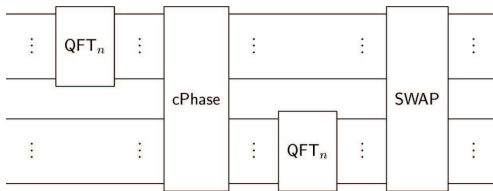
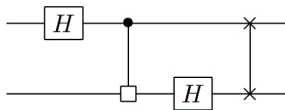
SP4: Dissemination

SP4: Perspectives

III. Local Control

Conclusions &
Outlook

■ **Principle:** from 2-qubit QFT to $2n$ -qubit QFT



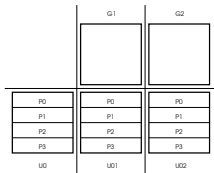


Parallelisation

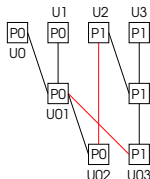
Speed-Up on High-Performance Parallel Cluster with T. Gradl, T. Huckle

■ Parallelising Matrix Operations

1. slice-wise:



2. tree-like:



■ Resulting Speed-Ups: 10 spins 128 time slices

128 AMD Opteron 850 CPU (2.4 GHz)

Subroutine	% of time	Speedup
optimizeCG	100	578
maxStepSize	90	709
getGradient	9.1	187
expm	7.5	879
propagation	1	31
gradient	0.6	81



Acknowledgements

Thanks go to:

Andreas Spörl
Gunther Dirr, Uwe Helmke
Frank Wilhelm, Markus Storcz, Johannes Ferber, Ville Bergholm
Tobias Gradl, Thomas Huckle
Navin Khaneja
Steffen J. Glaser

integrated EU programme QAP

References:

J. Magn. Reson. **172**, 296 (2005), *PRA* **72**, 043221 (2005),
EUROPAR Lect. Notes Comput. Sci. **4128**, 751 (2006), *PRA* **75**, 012302 (2007),
quant-ph/0609037, quant-ph/0610061, quant-ph/0612165,
math-ph/0701035, math-ph/0702005